

UNSUPERVISED LEARNING 2011

LECTURE :FACTOR ANALYSIS

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Based on Lecture Notes by A. Ng

Motivation

⊙ Distribution comes from MoG

- Have sufficient amount of data: $m \gg n$

dimension

num. of training points

- Use EM to fit Mixture of Gaussians

⊙ If $m \ll n$

- difficult to model a single Gaussian
- much less a mixture of Gaussian

Motivation

- m data points span only a low-dimensional subspace of \mathcal{R}^n
- ML estimator of Gaussian parameters:

$$\mu = \frac{1}{m} \sum_{i=1}^m x_i \quad \Sigma = \frac{1}{m} \sum_{i=1}^m (x_i - \mu)(x_i - \mu)^T$$

Singular

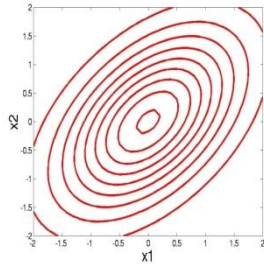
→ Can't compute Gaussian Density

- More generally, unless m exceeds n by some reasonable amount, the maximum likelihood estimates of the mean and covariance may be quite poor.

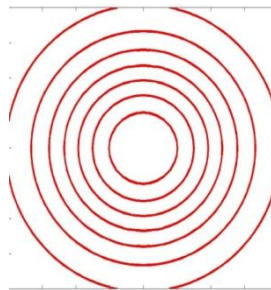
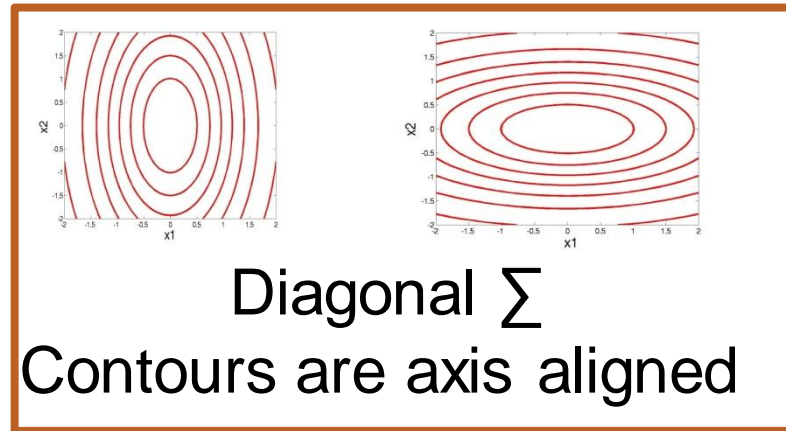
Restriction on Σ

- ◎ **Goal:** Fit a reasonable Gaussian model to the data when $m \ll n$.
- ◎ Possible solutions:
 - Limit the number of parameters, assume Σ is diagonal.
 - Limit $\Sigma = \sigma^2 I$, where σ^2 is the parameter under our control.

Contours of a Gaussian Density



General Σ

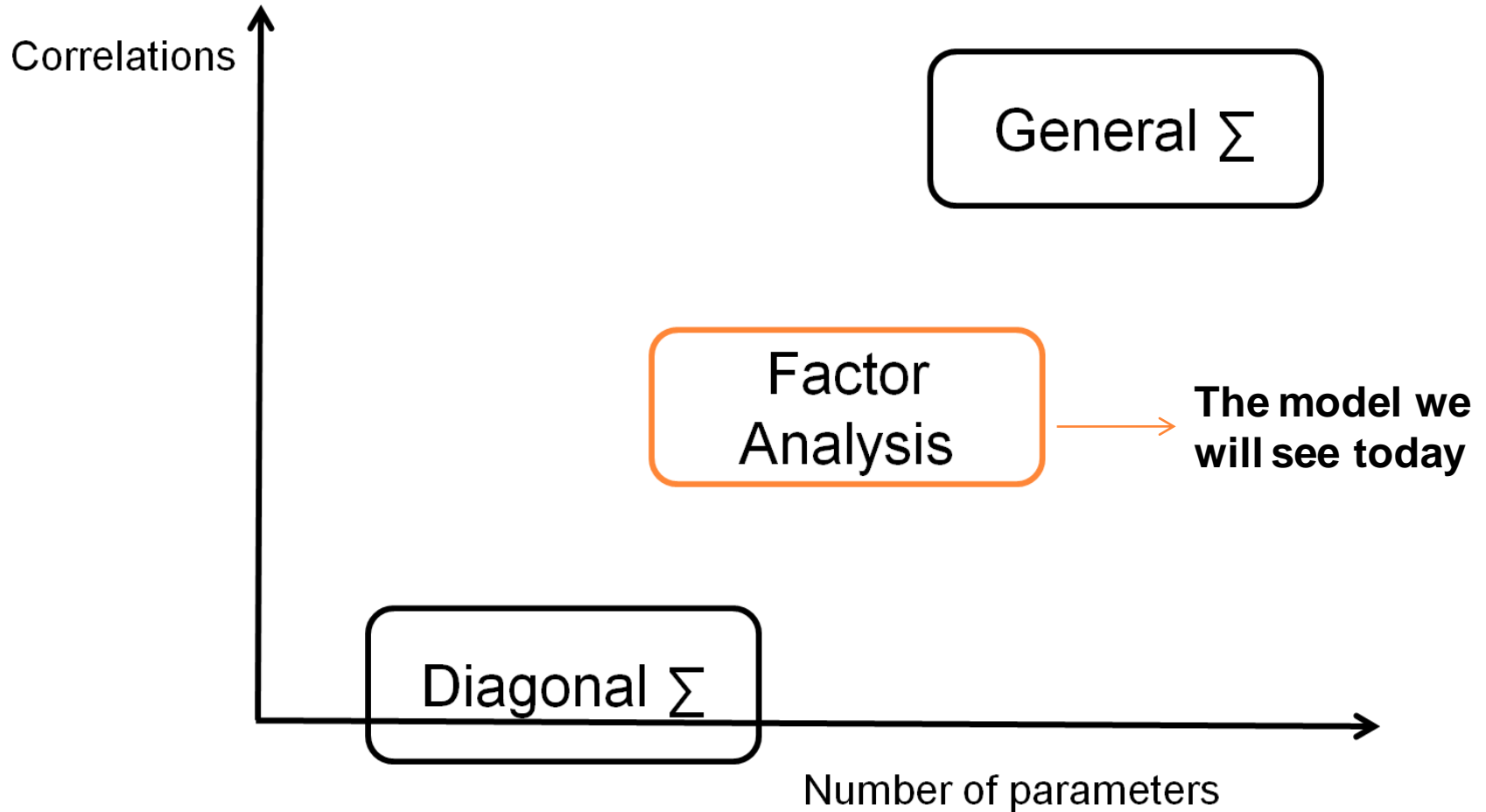


$$\Sigma = \sigma^2 I,$$

Correlation in the data

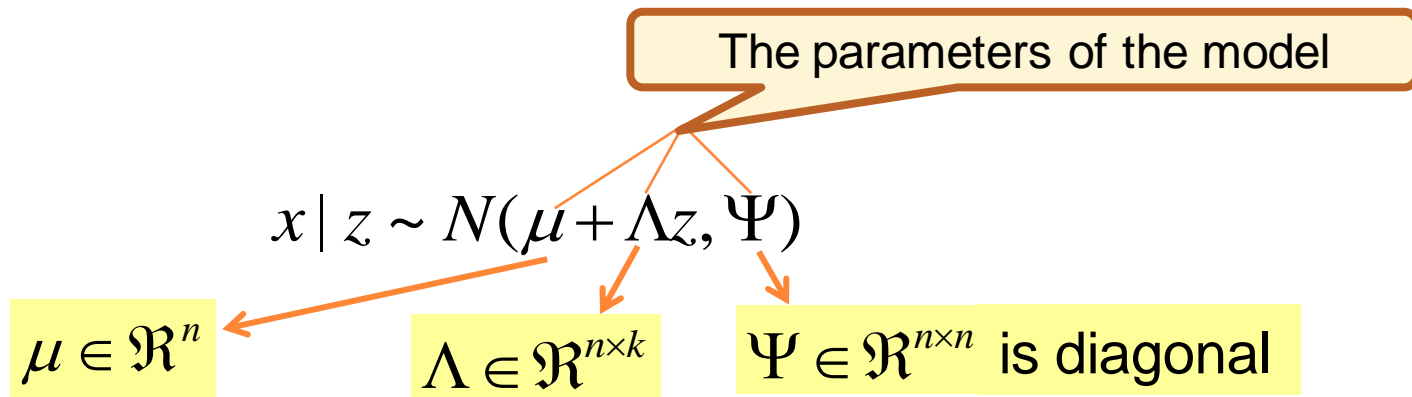
- ⦿ Restricting Σ to be diagonal means modelling the different coordinates of the data as being uncorrelated and independent.
- ⦿ Often, we would like to capture some interesting correlation structure in the data.

Modeling Correlation



Factor Analysis Model

Assume a latent random variable $z \in \mathbb{R}^k$ ($k < n$), $z \sim N(0, I)$



Equivalently,

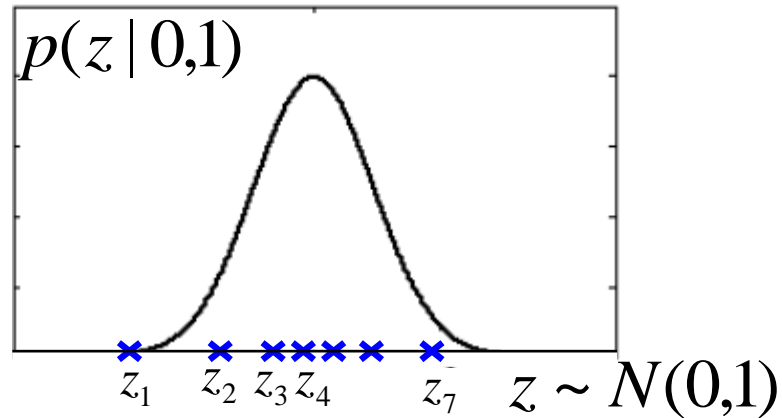
$$x = \mu + \Lambda z + \varepsilon$$

$\varepsilon \sim N(0, \Psi)$

z and ε are independent.

Example of the generative model of x

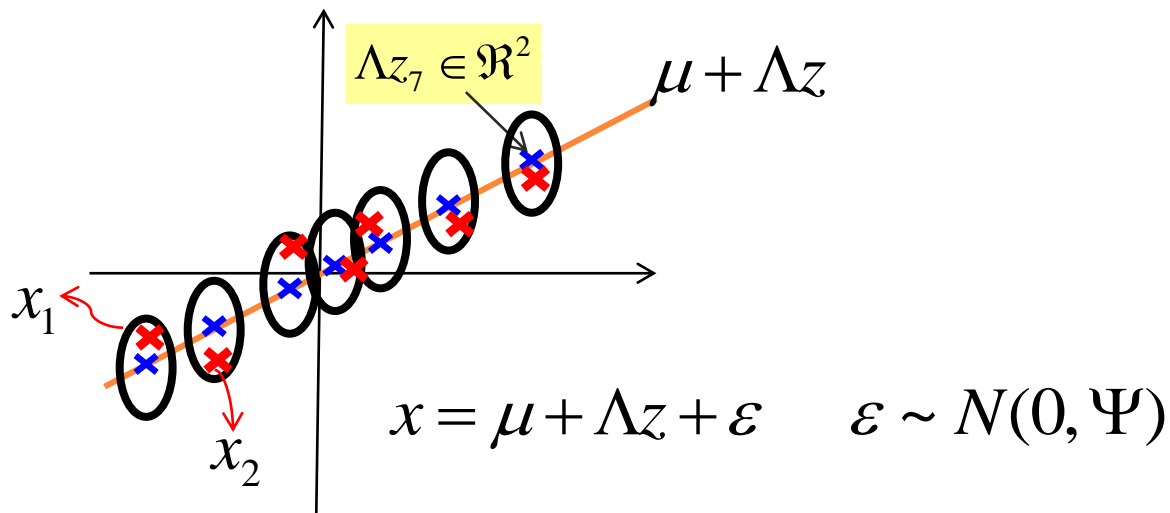
$$z \in \mathbb{R}^1, x \in \mathbb{R}^2$$



$$\Lambda = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Psi = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$



Generative process in higher dimensions

- We assume that each data point is generated by sampling a k -dimension multivariate Gaussian z_i .
- Then, it is mapped to a k -dimensional affine space of \mathcal{R}^n by computing $\mu + \Lambda z_i$.
- Lastly, x_i is generated by adding covariance Ψ noise to $\mu + \Lambda z_i$.

Definitions

Partitioned vector

- Suppose $x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ is r.v., where $x_1 \in \mathfrak{R}^r$, $x_2 \in \mathfrak{R}^s$, $x \in \mathfrak{R}^{r+s}$
- Suppose $x \sim N(\mu, \Sigma)$, where

$$\mu = \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}, \quad \Sigma = \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix}$$

Here $\mu_1 \in \mathfrak{R}^r$, $\mu_2 \in \mathfrak{R}^s$, $\Sigma_{11} \in \mathfrak{R}^{r \times r}$, $\Sigma_{12} \in \mathfrak{R}^{r \times s}$, ... and $\Sigma_{12} = \Sigma_{21}^T$

- Under our assumptions, x_1 and x_2 are jointly multivariate Gaussian.

Marginal distribution of x_1

$$p(x_1) = \int p(x_1, x_2) dx_2$$

Marginal distributions of Gaussians are themselves Gaussian, hence $x_1 \sim N(\mu_1, \Sigma_{11})$

By definition of the joint covariance of x_1 and x_2

$$\begin{aligned} \text{Cov}(x) = \Sigma &= \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix} = E[(x - \mu)(x - \mu)^T] = E \left[\begin{pmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{pmatrix} \begin{pmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{pmatrix}^T \right] \\ &= E \begin{bmatrix} (x_1 - \mu_1)(x_1 - \mu_1)^T & (x_1 - \mu_1)(x_2 - \mu_2)^T \\ (x_2 - \mu_2)(x_1 - \mu_1)^T & (x_2 - \mu_2)(x_2 - \mu_2)^T \end{bmatrix}. \end{aligned}$$

$$\text{Cov}(x_1) = E[(x_1 - \mu_1)(x_1 - \mu_1)^T] = \Sigma_{11}$$

Conditional distribution of x_1 given x_2

$$p(x_1 | x_2) = \frac{p(x_1, x_2)}{p(x_2)} \quad \begin{array}{l} \leftarrow N(\mu, \Sigma) \\ \leftarrow N(\mu_2, \Sigma_{22}) \end{array}$$

Referring to the definition of the multivariate Gaussian distribution, it can be shown that $x_1 | x_2 \sim N(\mu_{1|2}, \Sigma_{1|2})$, where

$$\mu_{1|2} = \mu_1 + \Sigma_{12} \Sigma_{22}^{-1} (x_2 - \mu_2),$$

$$\Sigma_{1|2} = \Sigma_{11} - \Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21}$$

Finding the Parameters of FA model

- Assume z and x have a joint Gaussian distribution:

$$\begin{bmatrix} x \\ z \end{bmatrix} \sim N(\mu_{zx}, \Sigma)$$

- We want to find μ_{zx} and Σ

$$E[z] = 0 \quad (\text{since } z \sim N(0, I))$$

$$E[x] = E[\mu + \Lambda z + \varepsilon] = \mu + \Lambda E[z] + E[\varepsilon] = \mu.$$

$$\mu_{zx} = E \begin{bmatrix} z \\ x \end{bmatrix} = \begin{bmatrix} \vec{0} \\ \mu \end{bmatrix} \begin{array}{l} \updownarrow k \\ \updownarrow n \end{array}$$

Finding Σ

⊙ We need to calculate

- upper left block

$$\Sigma_{zz} = E[(z - E[z])(z - E[z])^T]$$

- upper-right block

$$\Sigma_{zx} = E[(z - E[z])(x - E[x])^T]$$

- lower-right block

$$\Sigma_{xx} = E[(x - E[x])(x - E[x])^T]$$

$$z \sim N(0, I)$$

$$\Sigma_{zz} = \text{Cov}(z) = I$$

Finding Σ_{zx}

$$E[(z - \underbrace{E[z]}_{=0})(x - \underbrace{E[x]}_{\mu})^T] = E[z(\underbrace{\mu + \Lambda z + \varepsilon}_{\mu})^T]$$

$$= \underbrace{E[zz^T]}_{\parallel \text{Cov}(z)} + \underbrace{E[z\varepsilon^T]}_{\parallel \leftarrow \text{independent}} \\ E[z]E[\varepsilon] = 0$$

$$= \Lambda^T$$

Finding Σ_{xx}

Similarly,

$$\begin{aligned}\Sigma_{xx} &= E[(x - E[x])(x - E[x])^T] \\ &= E[(\mu + \Lambda z + \varepsilon - \mu)(\mu + \Lambda z + \varepsilon - \mu)^T] \\ &= E[\Lambda z z^T \Lambda^T + \varepsilon z^T \Lambda^T - \Lambda z \varepsilon^T + \varepsilon \varepsilon^T] \\ &= \Lambda E[z z^T] \Lambda^T + E[\varepsilon \varepsilon^T] = \Lambda \Lambda^T + \Psi\end{aligned}$$

Finding the parameters (cont.)

Putting everything together, we have that,

$$\begin{bmatrix} z \\ x \end{bmatrix} \sim N\left(\begin{bmatrix} \vec{0} \\ \mu \end{bmatrix}, \begin{bmatrix} I & \Lambda^T \\ \Lambda & \Lambda\Lambda^T + \Psi \end{bmatrix}\right)$$

We also see that the marginal distribution of x is given by

$$x \sim N(\mu, \Lambda\Lambda^T + \Psi)$$

Thus, given a training set $\{x_i\}_{i=1}^m$ log likelihood of the parameters is:

$$l(\mu, \Lambda, \Psi) = \log \prod_{i=1}^m \frac{1}{(2\pi)^{n/2} |\Lambda\Lambda^T + \Psi|} \exp\left(-\frac{1}{2} (x_i - \mu)^T (\Lambda\Lambda^T + \Psi) (x_i - \mu)\right)$$

Finding the parameters (cont.)

$$l(\mu, \Lambda, \Psi) = \log \prod_{i=1}^m \frac{1}{(2\pi)^{n/2} |\Lambda\Lambda^T + \Psi|} \exp\left(-\frac{1}{2}(x_i - \mu)^T (\Lambda\Lambda^T + \Psi)(x_i - \mu)\right)$$

- To perform maximum likelihood estimation, we would like to maximize this quantity with respect to the parameters.
- But maximizing this formula explicitly is hard, and we are aware of no algorithm that does so in closed-form.
- So, we will instead use the **EM algorithm**.

EM for Factor Analysis

⊙ E-step:

$$Q_i(z_i) = p(z_i | x_i, \theta)$$

⊙ M-step:

$$\theta = \arg \max_{\theta} \sum_i \int_{z_i} Q_i(z_i) \log \frac{p(x_i, z_i; \theta)}{Q_i(z_i)} dz_i$$

E-step (EM for FA)

- We need to compute $Q_i(z_i) = p(z_i | x_i; \mu, \Lambda, \Psi)$
- Using a conditional distribution of a Gaussian we find that $z_i | x_i \sim N(\mu_{z_i|x_i}, \Sigma_{z_i|x_i})$

$$\mu_{1|2} = \mu_1 + \Sigma_{12} \Sigma_{22}^{-1} (x_2 - \mu_2),$$

$$\Sigma_{1|2} = \Sigma_{11} - \Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21}$$

$$\Sigma = \begin{bmatrix} I & \Lambda^T \\ \Lambda & \Lambda \Lambda^T + \Psi \end{bmatrix}$$

$$\mu_{z_i|x_i} = \begin{matrix} \mu_1 & \Sigma_{12} & \Sigma_{22}^{-1} & (x_2 - \mu_2) \\ \vec{0} & -\Lambda^T & (\Lambda^T \Lambda + \Psi)^{-1} & (x_i - \mu) \end{matrix}$$

$$\Sigma_{z_i|x_i} = \begin{matrix} I & -\Lambda^T & (\Lambda^T \Lambda + \Psi)^{-1} & \Lambda \\ \Sigma_{11} & \Sigma_{12} & \Sigma_{22}^{-1} & \Sigma_{12} \end{matrix}$$

$$Q_i(z_i) = \frac{1}{(2\pi)^{2k} |\Sigma_{z_i|x_i}|^{1/2}} \exp\left(-\frac{1}{2} (z_i - \mu_{z_i|x_i})^T \Sigma_{z_i|x_i}^{-1} (z_i - \mu_{z_i|x_i})\right)$$

M-step (EM for FA)

Maximize:

$$\sum_{i=1}^m \int_{z_i} Q_i(z_i) \log \frac{p(x_i, z_i; \mu, \Lambda, \Psi)}{Q_i(z_i)} dz_i$$

with respect to the parameters μ, Λ, Ψ

- ◉ We will work out the optimization with respect to Λ
- ◉ Derivations of the updates for μ, Ψ is an exercise (Do it!)

Update for Λ

$$\sum_{i=1}^m \int_{z_i} Q_i(z_i) \log \frac{p(x_i, z_i; \mu, \Lambda, \Psi)}{Q_i(z_i)} dz_i$$

$$= \sum_{i=1}^m \int_{z_i} Q_i(z_i) [\log p(x_i | z_i; \mu, \Lambda, \Psi) + \log p(z_i) - \log Q_i(z_i)] dz_i$$

Expectation with respect to z_i , drawn from Q_i

$$= \sum_{i=1}^m E_{z_i \sim Q_i} [\log p(x_i | z_i; \mu, \Lambda, \Psi) + \log p(z_i) - \log Q_i(z_i)]$$

Update for Λ (cont.)

$$\sum_{i=1}^m E_{z_i \sim Q_i} [\log p(x_i | z_i; \mu, \Lambda, \Psi) + \log p(z_i) - \log Q_i(z_i)]$$

Remember that We want to maximize this expression with respect to Λ

$$\begin{aligned} & \sum_{i=1}^m E_{z_i \sim Q_i} [\log p(x_i | z_i; \mu, \Lambda, \Psi)] && x | z \sim N(\mu + \Lambda z, \Psi) \\ &= \sum_{i=1}^m E \left[\log \frac{1}{(2\pi)^{n/2} |\Psi|^{1/2}} \exp \left(-\frac{1}{2} (x_i - \mu - \Lambda z_i)^T \Psi^{-1} (x_i - \mu - \Lambda z_i) \right) \right] \\ &= \sum_{i=1}^m E \left[-\frac{1}{2} \log |\Psi| - \frac{n}{2} \log(2\pi) - \frac{1}{2} (x_i - \mu - \Lambda z_i)^T \Psi^{-1} (x_i - \mu - \Lambda z_i) \right] \end{aligned}$$

Do not depend on Λ

Update for Λ (cont.)

Take derivative with respect to Λ

$$\nabla_{\Lambda} \sum_{i=1}^m -E \left[\frac{1}{2} (x_i - \mu - \Lambda z_i)^T \Psi^{-1} (x_i - \mu - \Lambda z_i) \right] \rightarrow \text{scalar}$$

$$\text{tr} a = a, \quad a \in \mathfrak{R};$$

$$= \nabla_{\Lambda} \sum_{i=1}^m -E \left[\text{tr} \frac{1}{2} (x_i - \mu - \Lambda z_i)^T \Psi^{-1} (x_i - \mu - \Lambda z_i) \right]$$

Simplify:

$$= \sum_{i=1}^m \nabla_{\Lambda} E \left[-\text{tr} \frac{1}{2} z_i^T \Lambda^T \Psi^{-1} \Lambda z_i + \text{tr} z_i^T \Lambda^T \Psi^{-1} (x_i - \mu) \right]$$

Update for Λ (cont.)

$$\sum_{i=1}^m \nabla_{\Lambda} E \left[-\text{tr} \frac{1}{2} z_i^T \Lambda^T \Psi^{-1} \Lambda z_i + \text{tr} z_i^T \Lambda^T \Psi^{-1} (x_i - \mu) \right]$$

$$\text{tr} AB = \text{tr} BA$$

$$= \sum_{i=1}^m \nabla_{\Lambda} E \left[-\text{tr} \frac{1}{2} \Lambda^T \Psi^{-1} \Lambda z_i z_i^T + \text{tr} \Lambda^T \Psi^{-1} (x_i - \mu) z_i^T \right]$$

$$\nabla_{A^T} \text{tr} ABA^T C = B^T A^T C^T + B^T A^T C$$

$$= \sum_{i=1}^m E \left[-\Psi^{-1} \Lambda z_i z_i^T + \Psi^{-1} (x_i - \mu) z_i^T \right]$$

Update for Λ (cont.)

$$\sum_{i=1}^m E \left[-\Psi^{-1} \Lambda z_i z_i^T + \Psi^{-1} (x_i - \mu) z_i^T \right]$$

Setting this to zero and simplifying, we get:

$$\sum_{i=1}^m \Lambda E_{z_i \sim Q_i} [z_i z_i^T] = \sum_{i=1}^m (x_i - \mu) E_{z_i \sim Q_i} [z_i^T]$$

Solving for Λ , we obtain:

$$\Lambda = \left(\sum_{i=1}^m (x_i - \mu) E_{z_i \sim Q_i} [z_i^T] \right) \left(\sum_{i=1}^m E_{z_i \sim Q_i} [z_i z_i^T] \right)^{-1}$$

Since Q is Gaussian with mean $\mu_{z_i|x_i}$ and covariance $\Sigma_{z_i|x_i}$

$$E_{z_i \sim Q_i} [z_i^T] = \mu_{z_i|x_i}^T$$

$$E_{z_i \sim Q_i} [z_i z_i^T] = \mu_{z_i|x_i} \mu_{z_i|x_i}^T + \Sigma_{z_i|x_i}$$

$Cov(Y) = E[YY^T] - E[Y]E[Y^T]$
hence,
 $E[YY^T] = E[Y]E[Y^T] + Cov(Y)$

Update for Λ (cont.)

$$E_{z_i \sim Q_i} [z_i z_i^T] = \mu_{z_i|x_i} \mu_{z_i|x_i}^T + \Sigma_{z_i|x_i}$$

$$E_{z_i \sim Q_i} [z_i^T] = \mu_{z_i|x_i}^T$$



substitute

$$\Lambda = \left(\sum_{i=1}^m (x_i - \mu) E_{z_i \sim Q_i} [z_i^T] \right) \left(\sum_{i=1}^m E_{z_i \sim Q_i} [z_i z_i^T] \right)^{-1}$$

$$\Lambda = \left(\sum_{i=1}^m (x_i - \mu) \mu_{z_i|x_i}^T \right) \left(\sum_{i=1}^m \mu_{z_i|x_i} \mu_{z_i|x_i}^T + \Sigma_{z_i|x_i} \right)^{-1}$$

M-step updates for μ and Ψ

$$\mu = \frac{1}{m} \sum_{i=1}^m x_i$$

Doesn't depend on $Q_i(z_i) = p(z_i | x_i; \mu, \Lambda, \Psi)$, hence can be computed once for all the iterations .

$$\Phi = \frac{1}{m} \sum_{i=1}^m x_i x_i^T - x_i \mu_{z_i|x_i}^T \Lambda^T - \Lambda \mu_{z_i|x_i} x_i^T + \Lambda (\mu_{z_i|x_i} \mu_{z_i|x_i}^T + \Sigma_{z_i|x_i}) \Lambda^T$$

The diagonal

$$\Psi_{ii} = \Phi_{ii}$$

(contains only diagonal entries)

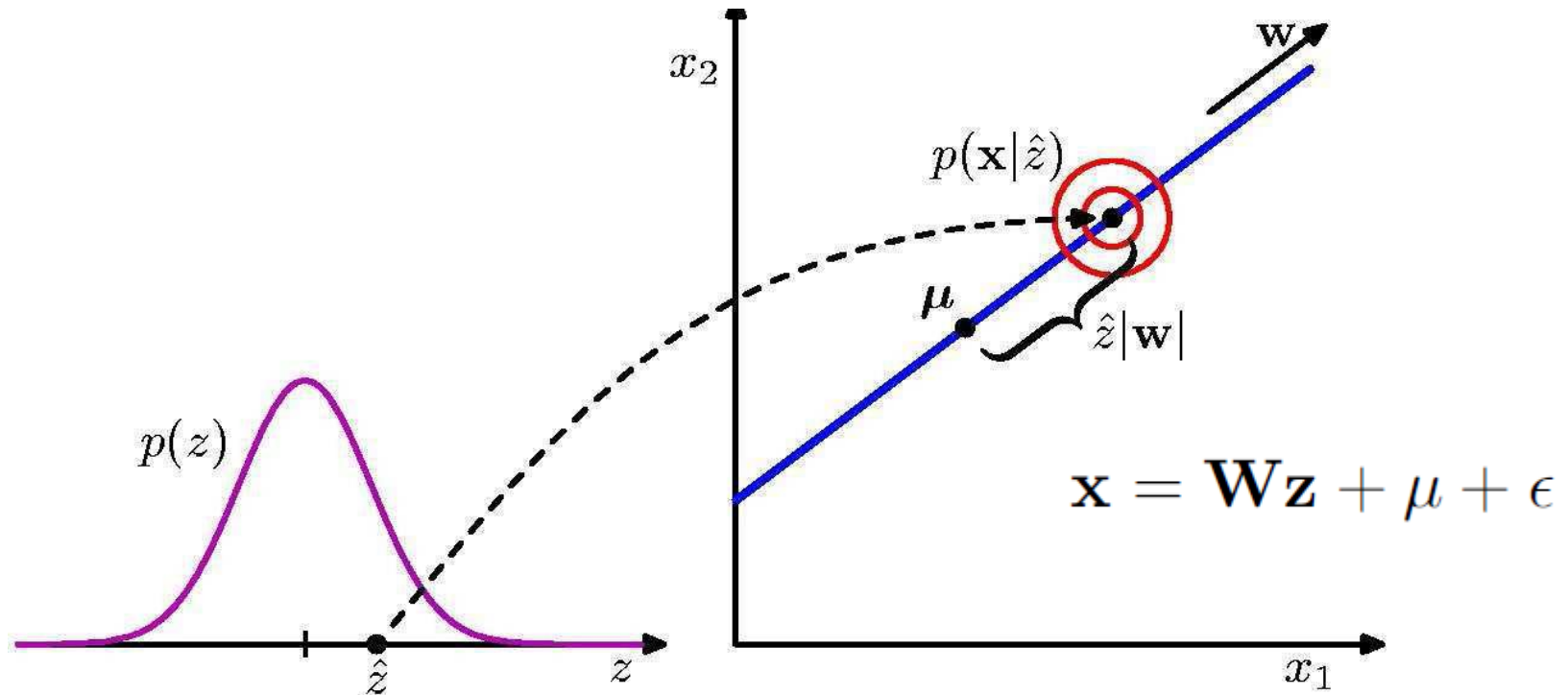
Probabilistic PCA

- Probabilistic, generative view of data

$$p(\mathbf{z}) = \mathcal{N}(\mathbf{z}|\mathbf{0}, \mathbf{I})$$

$$\mathbf{x} \in \mathbb{R}^D, \mathbf{z} \in \mathbb{R}^M$$

$$p(\mathbf{x}|\mathbf{z}) = \mathcal{N}(\mathbf{x}|\mathbf{W}\mathbf{z} + \mu, \sigma^2\mathbf{I})$$

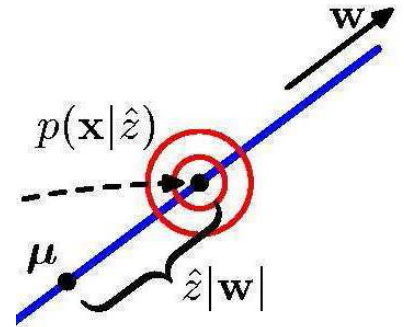


Compare

- Probabilistic PCA

$$p(\mathbf{z}) = \mathcal{N}(\mathbf{z}|\mathbf{0}, \mathbf{I})$$

$$p(\mathbf{x}|\mathbf{z}) = \mathcal{N}(\mathbf{x}|\mathbf{W}\mathbf{z} + \mu, \sigma^2\mathbf{I})$$

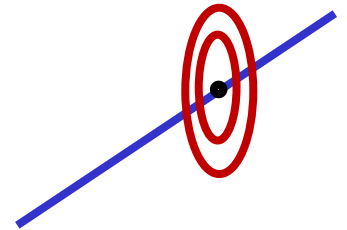


- FA

$$p(\mathbf{z}) = \mathcal{N}(\mathbf{z}|\mathbf{0}, \mathbf{I})$$

$$p(\mathbf{x}|\mathbf{z}) = \mathcal{N}(\mathbf{x}|\mathbf{W}\mathbf{z} + \mu, \Psi)$$

spherical



diagonal, axis-aligned

Probabilistic PCA

- ⊙ The columns of W are the principle components.
- ⊙ Can be found using
 - ML in closed form
 - EM (more efficient when only few eigenvectors are required, avoids evaluation of data covariance matrix)
 - Other advantages (see Bishop, Ch.12.2)