# Naïve Bayes Classifier 

## Lecture 12

## Unbiased Learning of Bayes Classifiers is Impractical

- Learn Bayes classifier by estimating $P(X \mid Y)$ and $P(Y)$.
- Assume $Y$ is boolean and $X$ is a vector of $n$ boolean attributes. In this case, we need to estimate a set of parameters $\quad \theta_{i j} \equiv P\left(X=x_{i} \mid Y=y_{j}\right)$
$i$ takes on $2^{n}$ possible values; $j$ takes on 2 possible values.
- How many parameters?
- For any particular value $y_{j}$, and the $2^{n}$ possible values of $x_{i}$, we need compute $2^{n-1}$ independent parameters.
- Given the two possible values for $Y$, we must estimate a total of 2(2n-1) such parameters.


## Complex model $\rightarrow$ High variance with limited data!!!

## Conditional Independence

- $X$ is conditionally independent of $Y$ given $Z$, if the probability distribution governing X is independent of the value of Y , given the value of Z

$$
(\forall i, j, k) P\left(X=x_{i} \mid Y=y_{i}, Z=z_{k}\right)=P\left(X=x_{i} \mid Z=z_{k}\right)
$$

- Example:
$P($ Thunder $\mid$ Rain, Lighting $)=P($ Thunder $\mid$ Lighting $)$ Note that in general Thunder is not independent of Rain, but it is given Lighting.
- Equivalent to:

$$
P(X, Y \mid Z)=P(X \mid Z) P(Y \mid Z)
$$

## Derivation of Naive Bayes Algorithm

- Naive Bayes algorithm assumes that the attributes $X_{1}, \ldots, X_{n}$ are all conditionally independent of one another, given $Y$. This dramatically simplifies
- the representation of $P(X \mid Y)$
- estimating $P(X \mid Y)$ from the training data.
- Consider $\mathrm{X}=\left(\mathrm{X}_{1}, \mathrm{X}_{2}\right)$

$$
P(X \mid Y)=P\left(X_{1}, X_{2} \mid Y\right)=P\left(X_{1} \mid Y\right) P\left(X_{2} \mid Y\right)
$$

- For X containing n attributes

$$
P(X \mid Y)=\prod_{i=1}^{n} P\left(X_{i} \mid Y\right)
$$

Given the boolean $X$ and $Y$, now we need only $2 n$ parameters to define $P(X \mid Y)$, which is dramatic reduction compared to the $2\left(2^{n-1}\right)$ parameters if we make no conditional independence assumption.

## The Naïve Bayes Classifier

- Given:
- Prior P(Y)
- $n$ conditionally independent features X , given the class Y
- For each $\mathrm{X}_{\mathrm{i}}$, we have likelihood $\mathrm{P}\left(\mathrm{X}_{\mathrm{i}} \mid \mathrm{Y}\right)$
- The probability that Y will take on its kth possible value, is

$$
P\left(Y=y_{k}\right) \prod P\left(X_{i} \mid Y=y_{k}\right)
$$

$$
P\left(Y=y_{k} \mid X\right)=\frac{\sum_{j} P\left(Y=y_{k}\right) \prod_{i} P\left(X_{i} \mid Y=y_{k}\right)}{\sum_{i}}
$$

- The Decision rule:

$$
y^{*}=\underset{y_{k}}{\arg \max } P\left(Y=y_{k}\right) \prod_{i} P\left(X_{i} \mid Y=y_{k}\right)
$$

If assumption holds, NB is optimal classifier!

## Naïve Bayes for the discrete inputs

- Given, n attributes $\mathrm{X}_{i}$ each taking on J possible discrete values and Y a discrete variable taking on K possible values.
- MLE for Likelihood $P\left(X_{i}=x_{i j} \mid Y=y_{k}\right)$ given a set of training examples $D$ :

$$
\hat{P}\left(X_{i}=x_{i j} \mid Y=y_{k}\right)=\frac{\# D\left\{X_{i}=x_{i j} \wedge Y=y_{k}\right\}}{\# D\left\{Y=y_{k}\right\}}
$$

where the $\# D\{x\}$ operator returns the number of elements in the set $D$ that satisfy property $x$.

- MLE for the prior

$$
\hat{P}\left(Y=y_{k}\right)=\frac{\# D\left\{Y=y_{k}\right\}}{|D| \longleftarrow} \text { number of elements } \begin{gathered}
\text { in the training set } D
\end{gathered}
$$

## NB Example

- Given, training data

| Day | Outlook | Temperature | Humidity | Wind | PlayTennis |
| :---: | :---: | :---: | :---: | :---: | :---: |
| D1 | Sunny | Hot | High | Weak | No |
| D2 | Sunny | Hot | High | Strong | No |
| D3 | Overcast | Hot | High | Weak | Yes |
| D4 | Rain | Mild | High | Weak | Yes |
| D5 | Rain | Cool | Normal | Weak | Yes |
| D6 | Rain | Cool | Normal | Strong | No |
| D7 | Overcast | Cool | Normal | Strong | Yes |
| D8 | Sunny | Mild | High | Weak | No |
| D9 | Sunny | Cool | Normal | Weak | Yes |
| D10 | Rain | Mild | Normal | Weak | Yes |
| D11 | Sunny | Mild | Normal | Strong | Yes |
| D12 | Overcast | Mild | High | Strong | Yes |
| D13 | Overcast | Hot | Normal | Weak | Yes |
| D14 | Rain | Mild | High | Strong | No |

- Classify the following novel instance :
(Outlook=sunny, Temp=cool,Humidity=high,Wind=strong)


## NB Example

$y_{N B}=\arg \max P\left(y_{j}\right) P\left(\right.$ Outlook $\left.=\operatorname{sunny} \mid y_{j}\right) P\left(\right.$ Temp $\left.=\operatorname{cool} \mid y_{j}\right)$ $y_{j}=\{$ yes,no $\}$

$$
P\left(\text { Humidity }=\text { high } \mid y_{j}\right) P\left(\text { Wind }=\text { strong } \mid y_{j}\right)
$$

Priors:

$$
\begin{aligned}
& P(\text { PlayTennis }=\text { yes })=9 / 14=0.64 \\
& P(\text { PlayTennis }=\text { no })=5 / 14=0.36
\end{aligned}
$$

Conditional Probabilities, e.g. Wind $=$ strong :
$P($ Wind $=$ strong $\mid$ PlayTennis $=$ yes $)=3 / 9=0.33$
$P($ Wind $=$ strong $\mid$ PlayTennis $=n o)=3 / 5=0.6$
$P($ yes $) P($ sunny $\mid$ yes $) P($ cool $\mid$ yes $) P($ high $\mid$ yes $) P($ strong $\mid$ yes $)=0.0053$

$$
P(\text { no }) P(\text { sunny } \mid \text { no }) P(\text { cool } \mid \text { no }) P(\text { high } \mid \text { no }) P(\text { strong } \mid \text { no })=0.60
$$

## Subtleties of NB classifier 1 -Violating the NB assumption

- Usually, features are not conditionally independent.
- Nonetheless, NB often performs well, even when assumption is violated
- [Domingos\& Pazzani'96] discuss some conditions for good performance


## Subtleties of NB classifier 2 Insufficient training data

- What if you never see a training instance where $X_{1}=a$ when $Y=b$ ?
- e.g., $Y=\{$ SpamEmail $\}, X_{1}=\{$ 'Market' $\}$
- $P\left(X_{1}=a \mid Y=b\right)=0$
- Thus, no matter what the values $X_{2}, \ldots, X_{n}$ take:

$$
P\left(Y=b \mid X_{1}=a, X_{2}, \ldots, X_{n}\right)=0
$$

- Solution?


## Subtleties of NB classifier 2 Insufficient training data

- To avoid this, use a "smoothed" estimate
- effectively adds in a number of additional "hallucinated" examples
- assumes these hallucinated examples are spread evenly over the possible values of $X_{i}$.
- This smoothed estimate is given by

$$
\begin{gathered}
\hat{P}\left(X_{i}=x_{i j} \mid Y=y_{k}\right)=\frac{\# D\left\{X_{i}=x_{i j} \wedge Y=y_{k}\right\}+l}{\# D\left\{Y=y_{k}\right\}+l J} \\
\hat{P}\left(Y=y_{k}\right)=\frac{\# D\left\{Y=y_{k}\right\}+l}{|D|+l K} \quad \begin{array}{l}
\text { The number of } \\
\text { hallucinated examples }
\end{array}
\end{gathered}
$$

$l$ determines the strength of the smoothing
If $l=1$ called Laplace smoothing

## Cont...

- Denote

$$
\hat{P}\left(X_{i}=x_{i j} \mid Y=y_{k}\right)=\frac{\# D\left\{X_{i}=x_{i j} \wedge Y=y_{k}\right\}+l}{\frac{\# D\left\{Y=y_{k}\right\}}{\frac{\mathrm{n}}{\mid l J}}} \mathrm{~m}
$$

- Then

$$
\hat{P}\left(X_{i}=x_{i j} \mid Y=y_{k}\right)=\frac{n_{c}+m \frac{1}{J}}{n+m}
$$

- We can view it as a Bayesian approach to estimating the probability: $\hat{P}\left(X_{i}=x_{i j} \mid Y=y_{k}\right)=\frac{n_{c}+m p}{n+m}$ with uniform prior $p=\frac{1}{J}$
- The observed fraction and prior are combined with the weight m .


## Naive Bayes for Continuous Inputs

- When the $X_{i}$ are continuous we must choose some other way to represent the distributions $P\left(X_{i} \mid Y\right)$.
- One common approach is to assume that for each possible discrete value $y_{k}$ of $Y$, the distribution of each continuous $X_{i}$ is Gaussian.
- In order to train such a Naïve Bayes classifier we must estimate the mean and standard deviation of each of these Gaussians


## Naive Bayes for Continuous Inputs

- MLE for means

$$
\hat{\mu}_{i k}=\frac{1}{\sum_{j} \delta\left(Y^{j}=y_{k}\right)} \sum_{j} X_{i}^{j} \delta\left(Y^{j}=y_{k}\right)
$$

- where $j$ refers to the th training example, and where $\delta\left(Y=y_{k}\right)$ is 1 if $Y=y_{k}$ and 0 otherwise.
- Note the role of $\delta$ is to select only those training examples for which $Y=y_{k}$.
- MLE for standard deviation

$$
\hat{\sigma}_{i k}^{2}=\frac{1}{\sum_{j} \delta\left(Y^{j}=y_{k}\right)} \sum_{j}\left(X_{i}^{j}-\hat{\mu}_{i k}\right)^{2} \delta\left(Y^{j}=y_{k}\right)
$$

## Learning Classify Text

- Applications:
- Learn which news article are of interest
- Learn to classify web pages by topic.
- Naïve Bayes is among most effective algorithms
- Target concept Interesting?: Document->\{+,-\}

1 Represent each document by vector of words

- one attribute per word position in document

2 Learning: Use training examples to estimate

- $P(+)$
- P(-)
- P(doc|+)
- P(doc|-)


## Text Classification-Example:

## Text

Text Classification, or the task of automatically assigning semantic categories to natural language text, has become one of the key methods for organizing online information. Since hand-coding classification rules is costly or even impractical, most modern approaches employ machine learning techniques to automatically learn text classifiers from examples.

## The text contains 48 words

Note: Text size may vary, but it will not cause a problem

## NB conditional independence Assumption

$$
P\left(d o c \mid y_{j}\right)=\prod_{\substack{i=1 \\
\text { Indicates the kth word in } \\
\text { English vocabulary }}}^{\text {length }(d o c)} P\left(a_{i}=w_{k} \mid y_{j}\right) \begin{aligned}
& \text { probability that word in } \\
& \text { position } i \text { is } w_{k} \text {, given } y_{j}
\end{aligned}
$$

The NB assumption is that the word probabilities for one text position are independent of the words in other positions, given the document classification $y_{j}$

Clearly not true: The probability of word "learning" may be greater if the preceding word is "machine"

Necessary, without it the number of probability terms is prohibitive

Performs remarkably well despite the incorrectness of the assumption

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## Classification:

$$
\begin{aligned}
y^{*} & =\underset{y_{j} \in\{+,-\}}{\arg \max } P\left(y_{j}\right) P\left(a_{1}=\text { 'text' } \mid y_{j}\right) \ldots P\left(a_{48}=\text { 'examples' } \mid y_{j}\right) \\
& =\underset{y_{j} \in\{+,-\}}{\arg \max } P\left(y_{j}\right) \prod_{i} P\left(a_{i}=w_{k} \mid y_{j}\right)
\end{aligned}
$$

## Estimating Likelihood

- Is problematic because we need to estimate it for each combination of text position, English word, and target value: $48 * 50,000 * 2 \approx 5$ million such terms.
- Assumption that reduced the number of terms Bag of Words Model
- The probability of encountering a specific word $w_{k}$ is independent of the specific word position.

$$
P\left(a_{i}=w_{k} \mid y_{j}\right)=P\left(a_{m}=w_{k} \mid y_{j}\right), \quad \forall i, m
$$

- Instead of estimating $P\left(a_{1}=w_{k} \mid y_{j}\right), P\left(a_{k}=w_{k} \mid y_{j}\right), \ldots$ we estimate a single term $P\left(w_{k} \mid y_{j}\right)$
- Now we have 50,000*2 distinct terms.


## Estimating Likelihood

- The estimate for the likelihood is

$$
P\left(w_{k} \mid y_{j}\right)=\frac{n_{k}+1}{n+\mid \text { Vocabulary } \mid}
$$

$n$-the total number of word positions in all training examples whose target value is $y_{j}$
$n_{k}$-the number times word $w_{k}$ is found among these $n$ word positions.
|Vocabulary| -the total number of distinct words found within the training data.

Learn_naive_Bayes_text(Examples, $V$ )

1. collect all words and other tokens that occur in Examples

- Vocabulary $\leftarrow$ all distinct words and other tokens in Examples

2. calculate the required $P\left(v_{j}\right)$ and $P\left(w_{k} \mid v_{j}\right)$ probability terms

- For each target value $v_{j}$ in $V$ do
- docs $_{j} \leftarrow$ subset of Examples for which the target value is $v_{j}$
$-P\left(v_{j}\right) \leftarrow \frac{\mid \text { docs }{ }_{j} \mid}{\mid \text { Examples } \mid}$
- Text $_{j} \leftarrow$ a single document created by concatenating all members of $\operatorname{docs}_{j}$
$-n \leftarrow$ total number of words in Text $_{j}$ (counting duplicate words multiple times)
- for each word $w_{k}$ in Vocabulary
$* n_{k} \leftarrow$ number of times word $w_{k}$ occurs in Text ${ }_{j}$
$* P\left(w_{k} \mid v_{j}\right) \leftarrow \frac{n_{k}+1}{n+\mid \text { Vocalbulary }^{2} \mid}$


## Classify_Naive_Bayes_Text(Doc)

- positions $\leftarrow$ all word positions in Doc that contain tokens found in Vocabulary
- Return $y^{*}=\underset{y_{j} \in\{+,-\}}{\arg \max } P\left(v_{j}\right) \prod_{i \in \text { positions }} P\left(a_{i} \mid v_{j}\right)$

