

***Curse of Dimensionality,  
Dimensionality Reduction with PCA***

# Curse of Dimensionality: Overfitting

- If the number of features  $d$  is large, the number of samples  $n$ , may be too small for accurate parameter estimation.

- For example, covariance matrix has  $d^2$  parameters:

$$\Sigma = \begin{bmatrix} \sigma_1^2 & \cdots & \sigma_{1d} \\ \vdots & \ddots & \vdots \\ \sigma_{d1} & \cdots & \sigma_d^2 \end{bmatrix}$$

- For accurate estimation,  $n$  should be much bigger than  $d^2$ , otherwise model is too complicated for the data, **overfitting**:

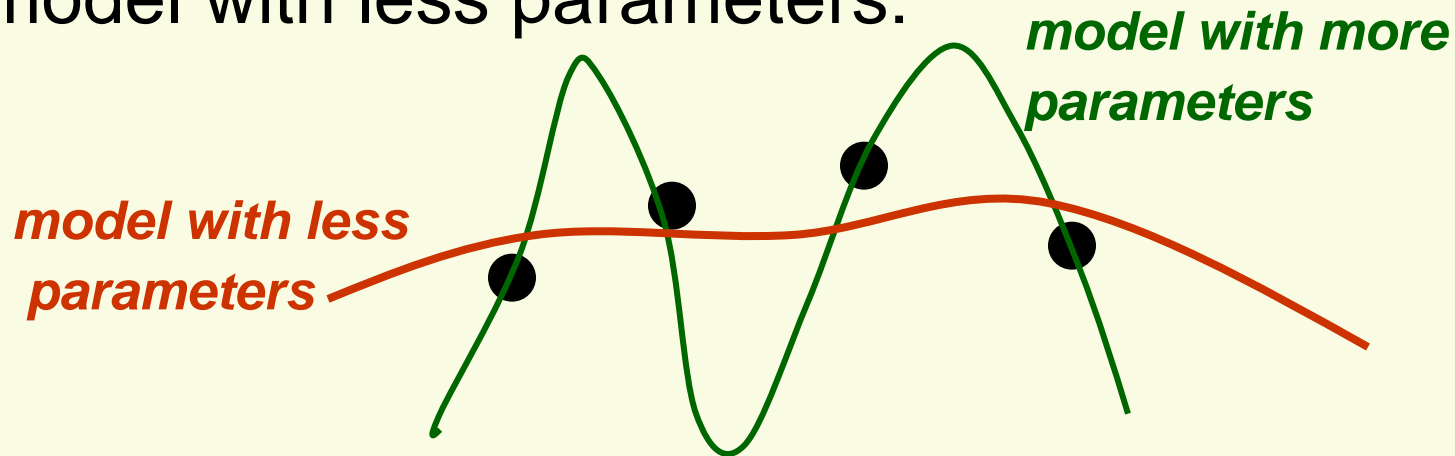
# Curse of Dimensionality: Overfitting

- Paradox: If  $n < d^2$  we are better off assuming that features are uncorrelated, even if we know this assumption is wrong
- In this case, the covariance matrix has only  $d$

parameters:

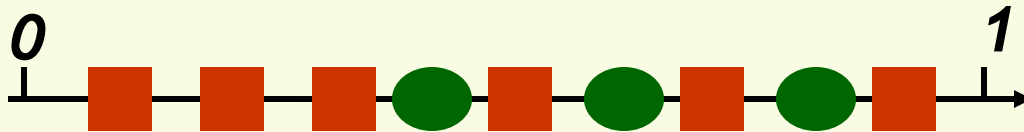
$$\Sigma = \begin{bmatrix} \sigma_1^2 & \dots & \mathbf{0} \\ \vdots & \ddots & \vdots \\ \mathbf{0} & \dots & \sigma_d^2 \end{bmatrix}$$

- We are likely to avoid overfitting because we fit a model with less parameters:



# Curse of Dimensionality: Number of Samples

- Suppose we want to use the nearest neighbor approach with  $k = 1$  (**1NN**)
- Suppose we start with only one feature

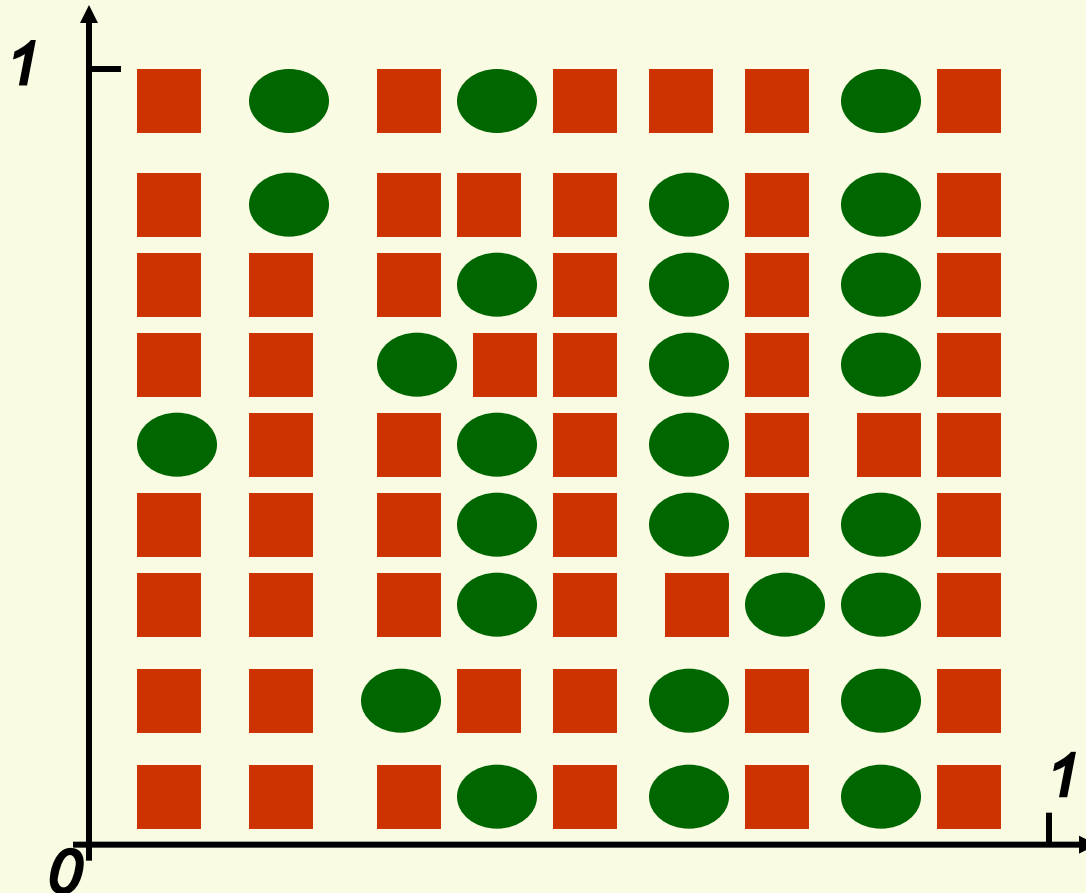


- This feature is not discriminative, i.e. it does not separate the classes well
- We decide to use 2 features. For the 1NN method to work well, need a lot of samples, i.e. samples have to be dense
- To maintain the same density as in 1D (9 samples per unit length), how many samples do we need?

# Curse of Dimensionality: Number of Samples

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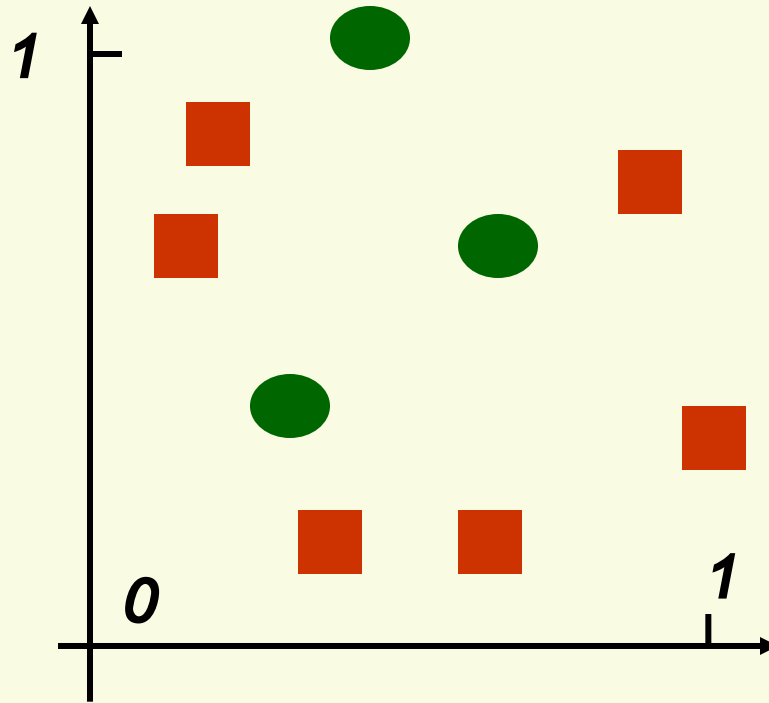
- We need  $9^2$  samples to maintain the same density as in  $1D$



# Curse of Dimensionality: Number of Samples

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- Of course, when we go from 1 feature to 2, no one gives us more samples, we still have 9

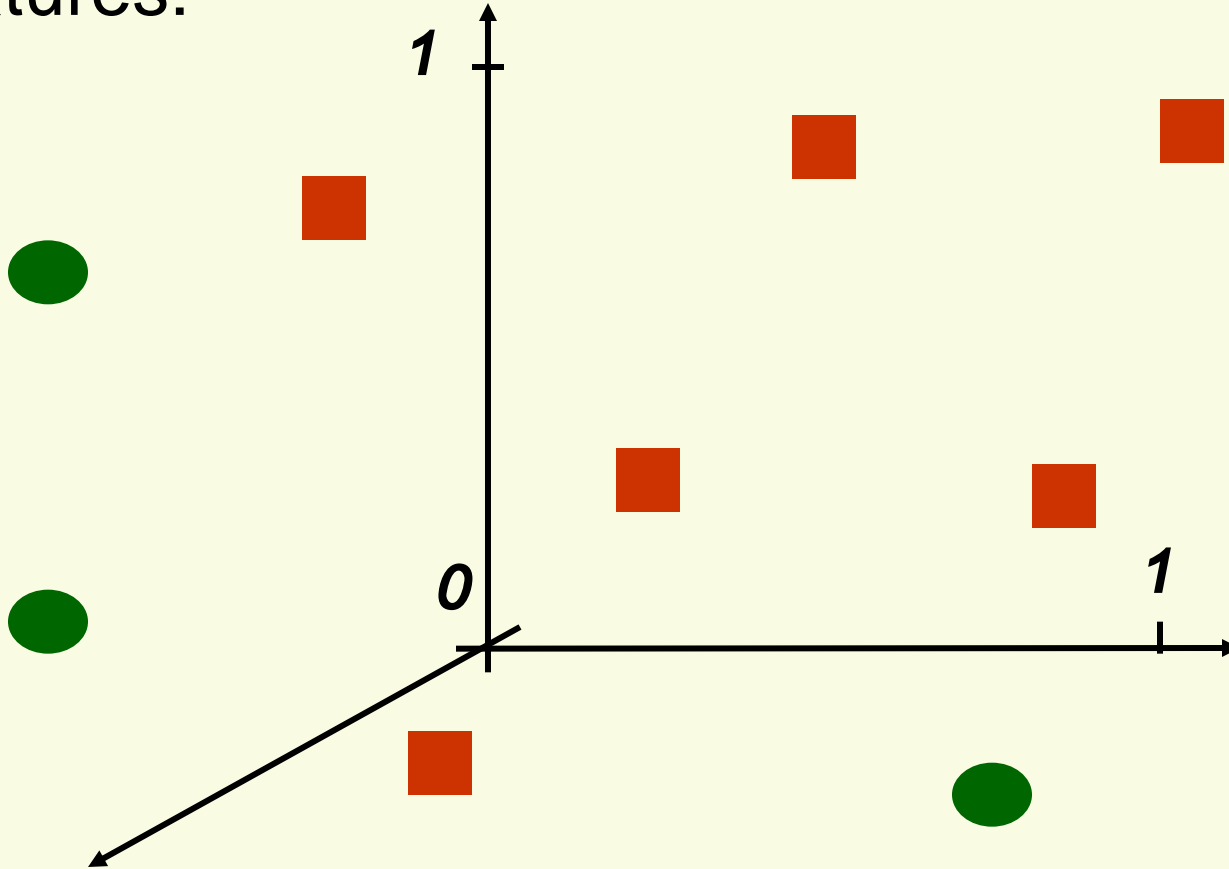


- This is way too sparse for **1NN** to work well

# Curse of Dimensionality: Number of Samples

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- Things go from bad to worse if we decide to use 3 features:



- If **9** was dense enough in 1D, in 3D we need  **$9^3=729$**  samples!

# *Curse of Dimensionality: Number of Samples*

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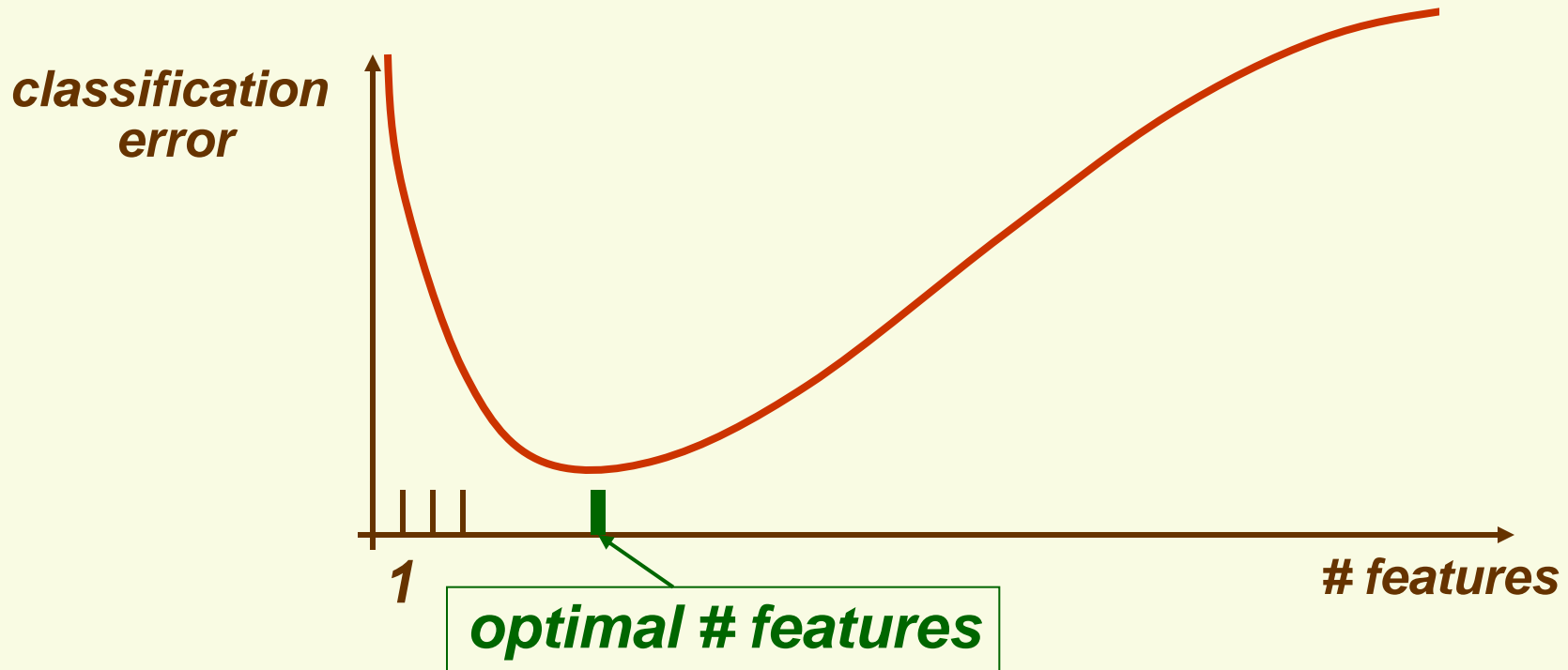
- In general, if  $n$  samples is dense enough in **1D**
- Then in  $d$  dimensions we need  $n^d$  samples!
- And  $n^d$  grows really really fast as a function of  $d$
- Common pitfall:
  - If we can't solve a problem with a few features, adding more features seems like a good idea
  - However the number of samples usually stays the same
  - The method with more features is likely to perform worse instead of expected better



# Curse of Dimensionality: Number of Samples

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- For a fixed number of samples, as we add features, the graph of classification error:



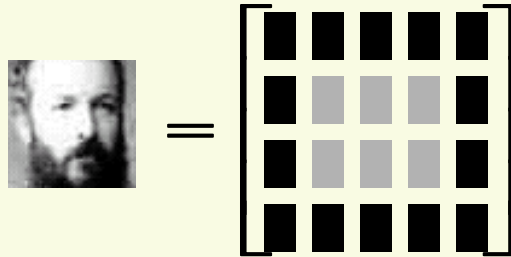
- Thus for each fixed sample size  $n$ , there is the optimal number of features to use

# The Curse of Dimensionality

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- We should try to avoid creating lot of features
- Often no choice, problem starts with many features
- Example: Face Detection

- One sample point is  $k$  by  $m$  array of pixels

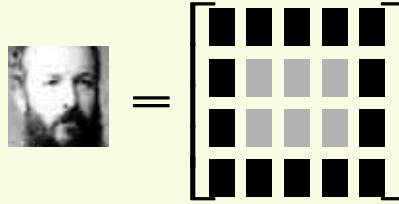


- Feature extraction is not trivial, usually every pixel is taken as a feature
- Typical dimension is 20 by 20 = 400
- Suppose **10** samples are dense enough for 1 dimension. Need only  $10^{400}$  samples

# The Curse of Dimensionality

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- Face Detection, dimension of one sample point is  $km$



- The fact that we set up the problem with  $km$  dimensions (features) does not mean it is really a  $km$ -dimensional problem
- Space of all  $k$  by  $m$  images has  $km$  dimensions
- Space of all  $k$  by  $m$  faces must be much smaller, since faces form a tiny fraction of all possible images
- Most likely we are not setting the problem up with the right features
- If we used better features, we are likely need much less than  $km$ -dimensions

# Dimensionality Reduction

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- High dimensionality is challenging and redundant
- It is natural to try to reduce dimensionality
- Reduce dimensionality by feature combination: combine old features  $\mathbf{x}$  to create new features  $\mathbf{y}$

$$\mathbf{x} = \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \\ \vdots \\ \mathbf{x}_d \end{bmatrix} \rightarrow f\left(\begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \\ \vdots \\ \mathbf{x}_d \end{bmatrix}\right) = \begin{bmatrix} \mathbf{y}_1 \\ \vdots \\ \mathbf{y}_k \end{bmatrix} = \mathbf{y} \quad \text{with } k < d$$

- For example, 
$$\mathbf{x} = \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \\ \mathbf{x}_3 \\ \mathbf{x}_4 \end{bmatrix} \rightarrow \begin{bmatrix} \mathbf{x}_1 + \mathbf{x}_2 \\ \mathbf{x}_3 + \mathbf{x}_4 \end{bmatrix} = \mathbf{y}$$

- Ideally, the new vector  $\mathbf{y}$  should retain from  $\mathbf{x}$  all information important for classification

# Dimensionality Reduction

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- The best  $f(\mathbf{x})$  is most likely a non-linear function
- Linear functions are easier to find though
- For now, assume that  $f(\mathbf{x})$  is a linear mapping
- Thus it can be represented by a matrix  $\mathbf{W}$ :

$$\begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \\ \vdots \\ \mathbf{x}_d \end{bmatrix} \Rightarrow \mathbf{W} \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \\ \vdots \\ \mathbf{x}_d \end{bmatrix} = \begin{bmatrix} \mathbf{w}_{11} & \cdots & \mathbf{w}_{1d} \\ \vdots & & \vdots \\ \mathbf{w}_{k1} & \cdots & \mathbf{w}_{kd} \end{bmatrix} \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \\ \vdots \\ \mathbf{x}_d \end{bmatrix} = \begin{bmatrix} \mathbf{y}_1 \\ \vdots \\ \mathbf{y}_k \end{bmatrix} \quad \text{with } k < d$$

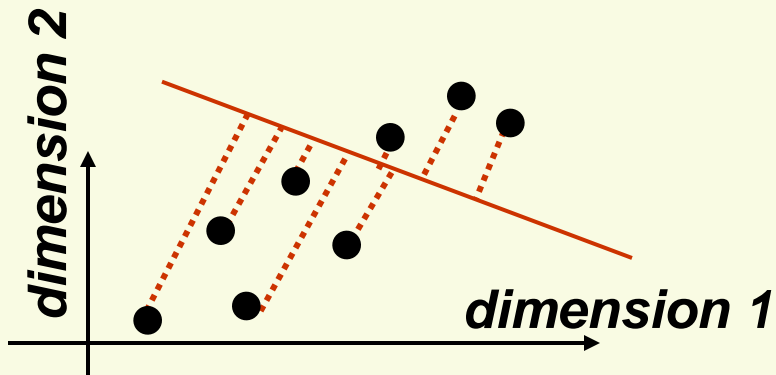
# *Feature Combination*

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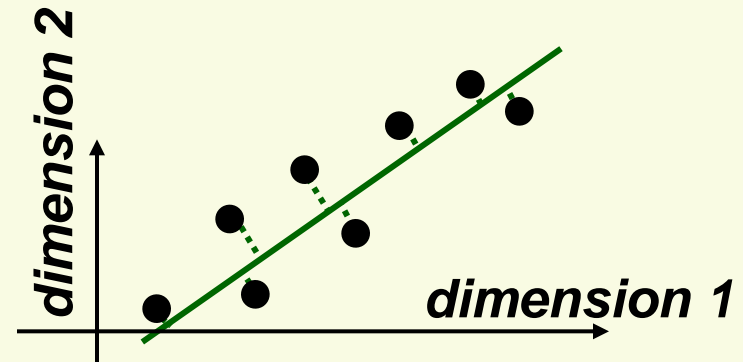
- We will look at 2 methods for feature combination
  - Principle Component Analysis (PCA)
  - Fischer Linear Discriminant (next lecture)

# Principle Component Analysis (PCA)

- **Main idea:** seek most accurate data representation in a lower dimensional space
- Example in 2-D
  - Project data to 1-D subspace (a line) which minimize the projection error



*large projection errors,  
bad line to project to*

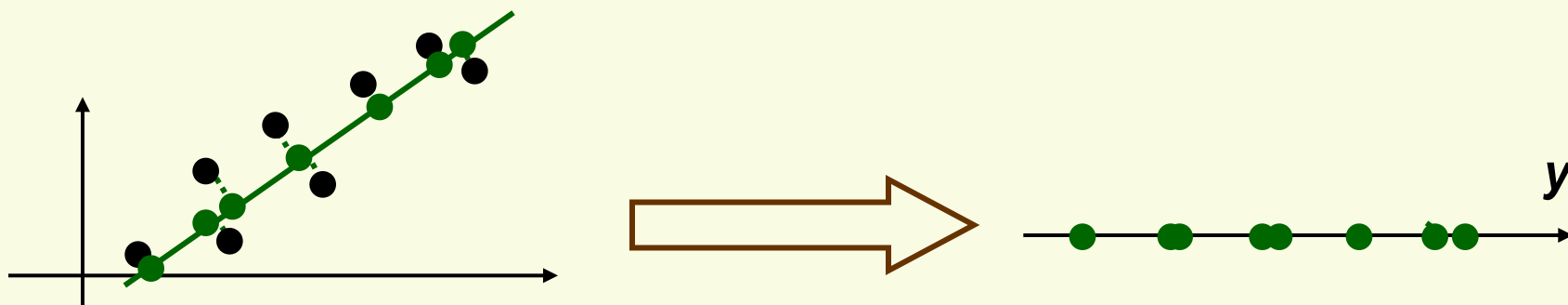


*small projection errors,  
good line to project to*

- Notice that the good line to use for projection lies in the direction of largest variance

# PCA

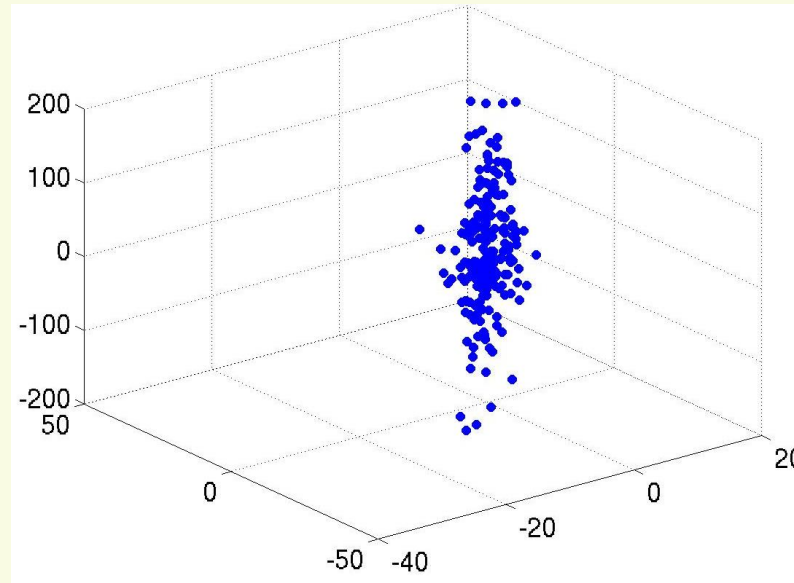
- After the data is projected on the best line, need to transform the coordinate system to get 1D representation for vector  $\mathbf{y}$



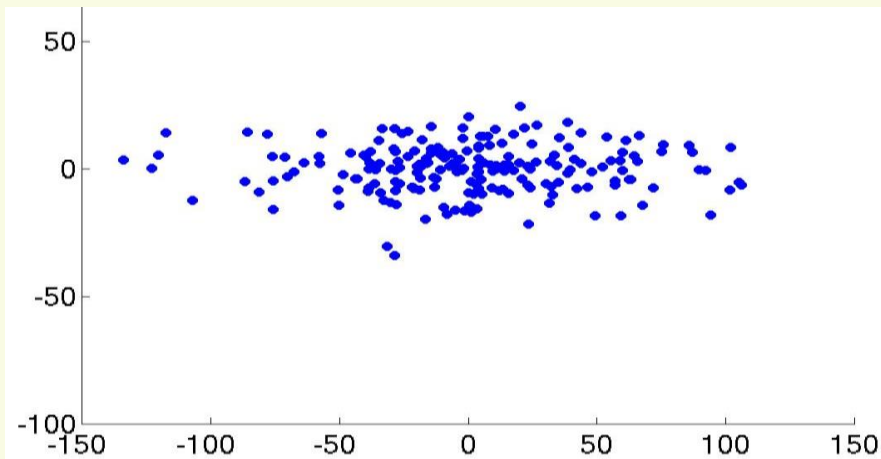
- Note that new data  $\mathbf{y}$  has the same variance as old data  $\mathbf{x}$  in the direction of the green line
- PCA preserves largest variances in the data. We will prove this statement, for now it is just an intuition of what PCA will do



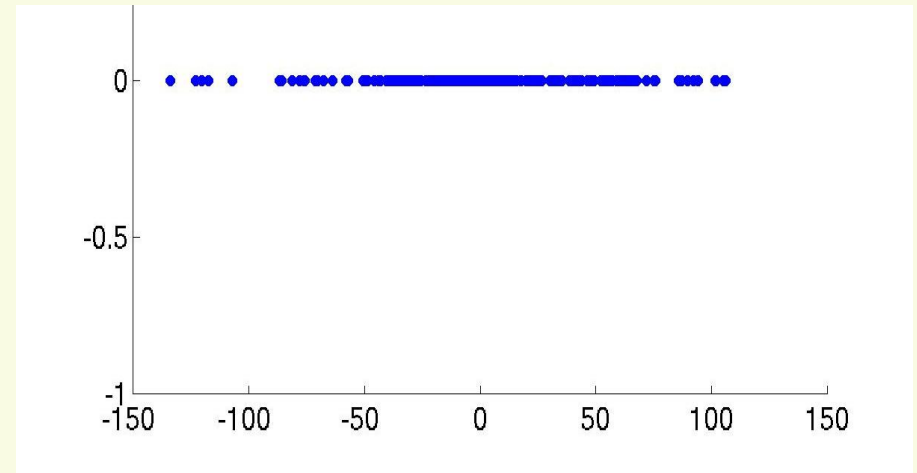
# PCA: Approximation of Elliptical Cloud in 3D



*best 2D approximation*



*best 1D approximation*



# PCA: Linear Algebra for Derivation

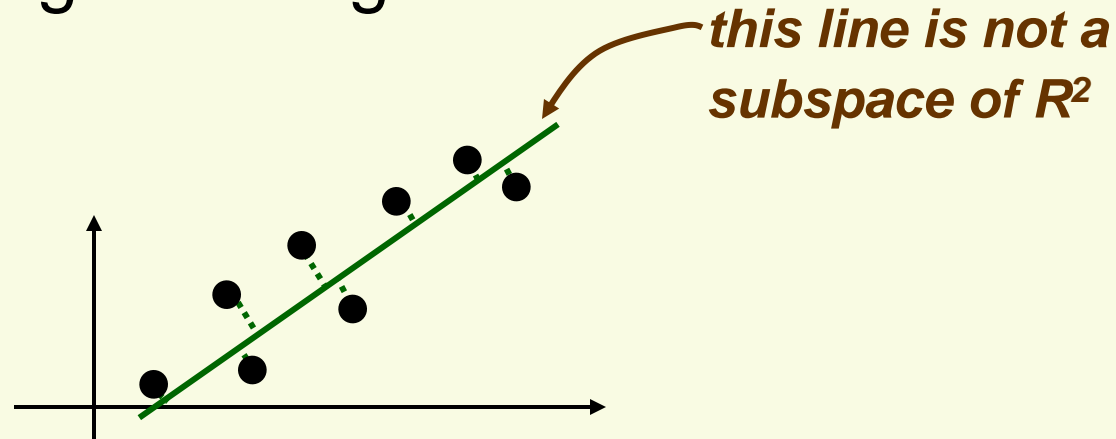
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- Let  $V$  be a  $d$  dimensional linear space, and  $W$  be a  $k$  dimensional linear subspace of  $V$
- We can always find a set of  $k$  dimensional vectors  $\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_k\}$  which forms an orthonormal basis for  $W$ 
  - $\langle \mathbf{e}_i, \mathbf{e}_j \rangle = 0$  if  $i$  is not equal to  $j$  and  $\langle \mathbf{e}_i, \mathbf{e}_i \rangle = 1$
- Thus any vector in  $W$  can be written as

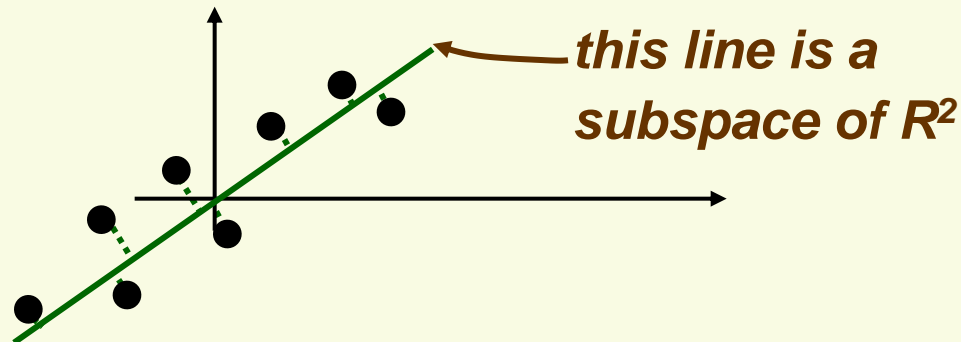
$$\alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \dots + \alpha_k \mathbf{e}_k = \sum_{i=1}^k \alpha_i \mathbf{e}_i \quad \text{for scalars } \alpha_1, \dots, \alpha_k$$

# PCA: Linear Algebra for Derivation

- Recall that subspace  $W$  contains the zero vector, i.e. it goes through the origin



- For derivation, it will be convenient to project to subspace  $W$ : thus we need to shift everything



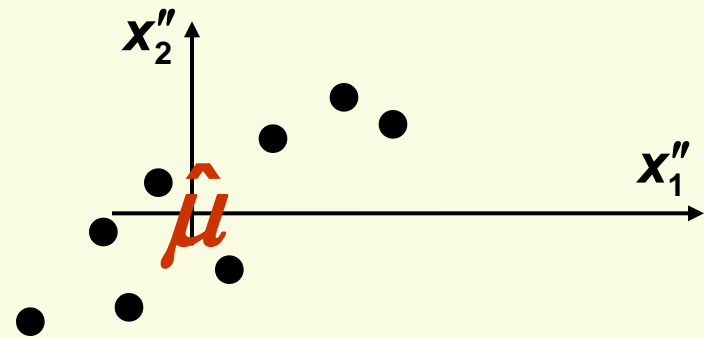
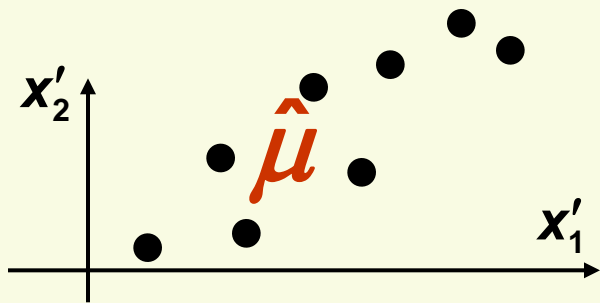
# PCA Derivation: Shift by the Mean Vector

- Before PCA, subtract sample mean from the data

$$\mathbf{x} - \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i = \mathbf{x} - \hat{\boldsymbol{\mu}}$$

- The new data has zero mean.

- All we did is change the coordinate system



# PCA: Derivation

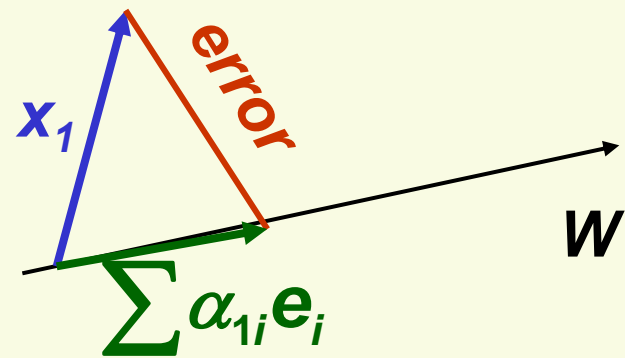
- We want to find the most accurate representation of data  $D = \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$  in some subspace  $W$  which has dimension  $k < d$

- Let  $\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_k\}$  be the orthonormal basis for  $W$ . Any vector in  $W$  can be written as  $\sum_{i=1}^k \alpha_i \mathbf{e}_i$

- Thus  $\mathbf{x}_1$  will be represented by some vector in  $W$   
$$\sum_{i=1}^k \alpha_{1i} \mathbf{e}_i$$

- Error of this representation:

$$\mathbf{error} = \left\| \mathbf{x}_1 - \sum_{i=1}^k \alpha_{1i} \mathbf{e}_i \right\|^2$$



# PCA: Derivation

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- To find the total error, we need to sum over all  $\mathbf{x}_j$ 's
- Any  $\mathbf{x}_j$  can be written as  $\sum_{i=1}^k \alpha_{ji} \mathbf{e}_i$
- Thus the total error for representation of all data  $\mathbf{D}$  is:

*sum over all data points*

$$\underbrace{J(\mathbf{e}_1, \dots, \mathbf{e}_k, \alpha_{11}, \dots, \alpha_{nk})}_{\text{unknowns}} = \sum_{j=1}^n \left\| \mathbf{x}_j - \sum_{i=1}^k \alpha_{ji} \mathbf{e}_i \right\|^2$$

*error at one point*

# PCA: Derivation

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- To minimize  $J$ , need to take partial derivatives and also enforce constraint that  $\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_k\}$  are orthogonal

$$J(\mathbf{e}_1, \dots, \mathbf{e}_k, \alpha_{11}, \dots, \alpha_{nk}) = \sum_{j=1}^n \left\| \mathbf{x}_j - \sum_{i=1}^k \alpha_{ji} \mathbf{e}_i \right\|^2$$

- Let us simplify  $J$  first:

$$J(\mathbf{e}_1, \dots, \mathbf{e}_k, \alpha_{11}, \dots, \alpha_{nk}) = \sum_{j=1}^n \|\mathbf{x}_j\|^2 - 2 \sum_{j=1}^n \sum_{i=1}^k \alpha_{ji} \mathbf{x}_j^t \mathbf{e}_i + \sum_{j=1}^n \sum_{i=1}^k \alpha_{ji}^2$$

# PCA: Derivation

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$$J(\mathbf{e}_1, \dots, \mathbf{e}_k, \alpha_{11}, \dots, \alpha_{nk}) = \sum_{j=1}^n \|\mathbf{x}_j\|^2 - 2 \sum_{j=1}^n \sum_{i=1}^k \alpha_{ji} \mathbf{x}_j^t \mathbf{e}_i + \sum_{j=1}^n \sum_{i=1}^k \alpha_{ji}^2$$

- First take partial derivatives with respect to  $\alpha_{ml}$

$$\frac{\partial}{\partial \alpha_{ml}} J(\mathbf{e}_1, \dots, \mathbf{e}_k, \alpha_{11}, \dots, \alpha_{nk}) = -2 \mathbf{x}_m^t \mathbf{e}_l + 2 \alpha_{ml}$$

- Thus the optimal value for  $\alpha_{ml}$  is

$$-2 \mathbf{x}_m^t \mathbf{e}_l + 2 \alpha_{ml} = 0 \Rightarrow \alpha_{ml} = \mathbf{x}_m^t \mathbf{e}_l$$



# PCA: Derivation

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$$J(\mathbf{e}_1, \dots, \mathbf{e}_k, \alpha_{11}, \dots, \alpha_{nk}) = \sum_{j=1}^n \|\mathbf{x}_j\|^2 - 2 \sum_{j=1}^n \sum_{i=1}^k \alpha_{ji} \mathbf{x}_j^t \mathbf{e}_i + \sum_{j=1}^n \sum_{i=1}^k \alpha_{ji}^2$$

- Plug the optimal value for  $\alpha_{mi} = \mathbf{x}_m^t \mathbf{e}_i$  back into  $J$

$$J(\mathbf{e}_1, \dots, \mathbf{e}_k) = \sum_{j=1}^n \|\mathbf{x}_j\|^2 - 2 \sum_{j=1}^n \sum_{i=1}^k (\mathbf{x}_j^t \mathbf{e}_i) \mathbf{x}_j^t \mathbf{e}_i + \sum_{j=1}^n \sum_{i=1}^k (\mathbf{x}_j^t \mathbf{e}_i)^2$$

- Can simplify  $J$

$$J(\mathbf{e}_1, \dots, \mathbf{e}_k) = \sum_{j=1}^n \|\mathbf{x}_j\|^2 - \sum_{j=1}^n \sum_{i=1}^k (\mathbf{x}_j^t \mathbf{e}_i)^2$$

# PCA: Derivation

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$$J(\mathbf{e}_1, \dots, \mathbf{e}_k) = \sum_{j=1}^n \|\mathbf{x}_j\|^2 - \sum_{j=1}^n \sum_{i=1}^k (\mathbf{x}_j^t \mathbf{e}_i)^2$$

- Rewrite  $J$  using  $(\mathbf{a}^t \mathbf{b})^2 = (\mathbf{a}^t \mathbf{b})(\mathbf{a}^t \mathbf{b}) = (\mathbf{b}^t \mathbf{a})(\mathbf{a}^t \mathbf{b}) = \mathbf{b}^t (\mathbf{a} \mathbf{a}^t) \mathbf{b}$

$$\begin{aligned} J(\mathbf{e}_1, \dots, \mathbf{e}_k) &= \sum_{j=1}^n \|\mathbf{x}_j\|^2 - \sum_{i=1}^k \mathbf{e}_i^t \left( \sum_{j=1}^n (\mathbf{x}_j \mathbf{x}_j^t) \right) \mathbf{e}_i \\ &= \sum_{j=1}^n \|\mathbf{x}_j\|^2 - \sum_{i=1}^k \mathbf{e}_i^t \mathbf{S} \mathbf{e}_i \end{aligned}$$

- Where  $\mathbf{S} = \sum_{j=1}^n \mathbf{x}_j \mathbf{x}_j^t$
- $\mathbf{S}$  is called the scatter matrix, it is just  $n-1$  times the sample covariance matrix we have seen before

$$\hat{\Sigma} = \frac{1}{n-1} \sum_{j=1}^n (\mathbf{x}_j - \hat{\mu})(\mathbf{x}_j - \hat{\mu})^t$$

# PCA: Derivation

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$$J(\mathbf{e}_1, \dots, \mathbf{e}_k) = \underbrace{\sum_{j=1}^n \|\mathbf{x}_j\|^2}_{\text{constant}} - \sum_{i=1}^k \mathbf{e}_i^t \mathbf{S} \mathbf{e}_i$$

- Minimizing  $J$  is equivalent to maximizing  $\sum_{i=1}^k \mathbf{e}_i^t \mathbf{S} \mathbf{e}_i$
- We should also enforce constraints  $\mathbf{e}_i^t \mathbf{e}_i = 1$  for all  $i$
- Use the method of Lagrange multipliers, incorporate the constraints with undetermined  $\lambda_1, \dots, \lambda_k$
- Need to maximize new function  $u$

$$u(\mathbf{e}_1, \dots, \mathbf{e}_k) = \sum_{i=1}^k \mathbf{e}_i^t \mathbf{S} \mathbf{e}_i - \sum_{j=1}^k \lambda_j (\mathbf{e}_j^t \mathbf{e}_j - 1)$$

# PCA: Derivation

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$$u(\mathbf{e}_1, \dots, \mathbf{e}_k) = \sum_{i=1}^k \mathbf{e}_i^t \mathbf{S} \mathbf{e}_i - \sum_{j=1}^k \lambda_j (\mathbf{e}_j^t \mathbf{e}_j - 1)$$

- Compute the partial derivatives with respect to  $\mathbf{e}_m$

$$\frac{\partial}{\partial \mathbf{e}_m} u(\mathbf{e}_1, \dots, \mathbf{e}_k) = 2\mathbf{S}\mathbf{e}_m - 2\lambda_m \mathbf{e}_m = \mathbf{0}$$

**Note:**  $\mathbf{e}_m$  is a vector, what we are really doing here is taking partial derivatives with respect to each element of  $\mathbf{e}_m$  and then arranging them up in a linear equation

- Thus  $\lambda_m$  and  $\mathbf{e}_m$  are eigenvalues and eigenvectors of scatter matrix  $\mathbf{S}$

$$\mathbf{S}\mathbf{e}_m = \lambda_m \mathbf{e}_m$$

# PCA: Derivation

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$$J(\mathbf{e}_1, \dots, \mathbf{e}_k) = \sum_{j=1}^n \|\mathbf{x}_j\|^2 - \sum_{i=1}^k \mathbf{e}_i^t \mathbf{S} \mathbf{e}_i$$

- Let's plug  $\mathbf{e}_m$  back into  $J$  and use  $\mathbf{S} \mathbf{e}_m = \lambda_m \mathbf{e}_m$

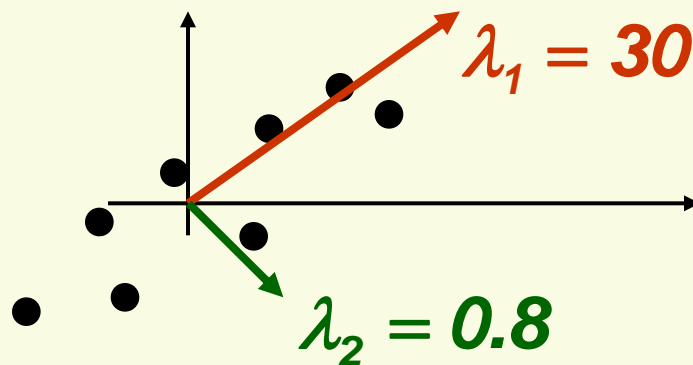
$$J(\mathbf{e}_1, \dots, \mathbf{e}_k) = \sum_{j=1}^n \|\mathbf{x}_j\|^2 - \sum_{i=1}^k \lambda_i \|\mathbf{e}_i\|^2 = \underbrace{\sum_{j=1}^n \|\mathbf{x}_j\|^2}_{\text{constant}} - \sum_{i=1}^k \lambda_i$$

- Thus to minimize  $J$  take for the basis of  $W$  the  $k$  eigenvectors of  $\mathbf{S}$  corresponding to the  $k$  largest eigenvalues

# PCA

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- The larger the eigenvalue of  $\mathbf{S}$ , the larger is the variance in the direction of corresponding eigenvector

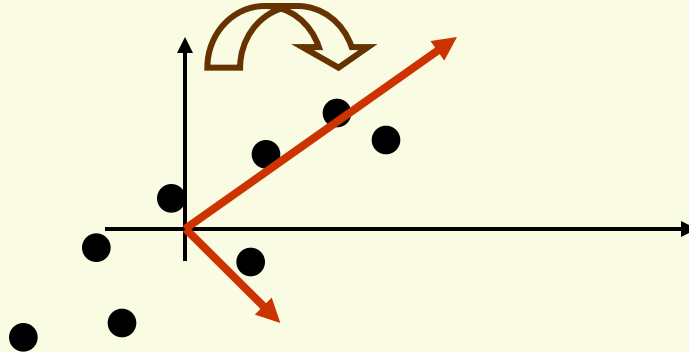


- This result is exactly what we expected: project  $\mathbf{x}$  into subspace of dimension  $\mathbf{k}$  which has the largest variance
- This is very intuitive: restrict attention to directions where the scatter is the greatest

# PCA

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- Thus PCA can be thought of as finding new orthogonal basis by rotating the old axis until the directions of maximum variance are found



# PCA as Data Approximation

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- Let  $\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_d\}$  be all  $d$  eigenvectors of the scatter matrix  $\mathbf{S}$ , sorted in order of decreasing corresponding eigenvalue

- Without any approximation, for any sample  $\mathbf{x}_i$ :

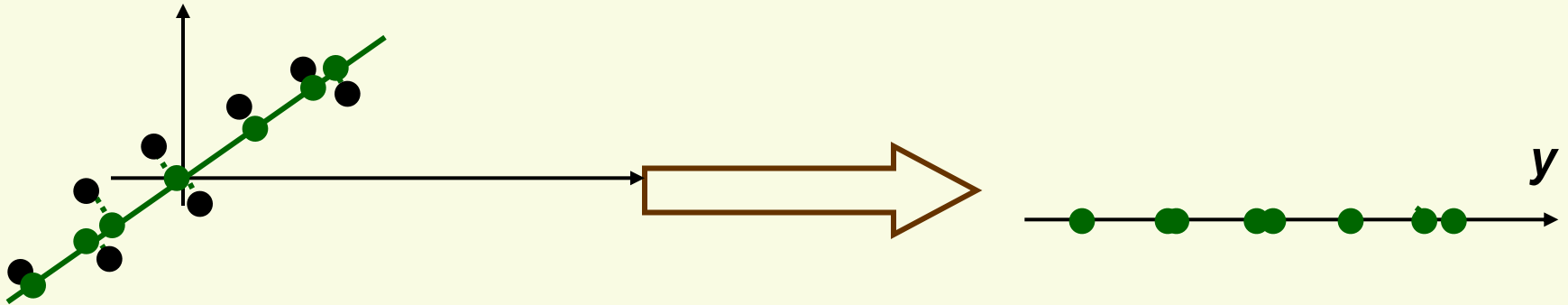
$$\mathbf{x}_i = \sum_{j=1}^d \alpha_j \mathbf{e}_j = \underbrace{\alpha_1 \mathbf{e}_1 + \dots + \alpha_k \mathbf{e}_k}_{\text{approximation of } \mathbf{x}_i} + \underbrace{\alpha_{k+1} \mathbf{e}_{k+1} \dots + \alpha_d \mathbf{e}_d}_{\text{error of approximation}}$$

- coefficients  $\alpha_m = \mathbf{x}_i^t \mathbf{e}_m$  are called *principle components*
  - The larger  $k$ , the better is the approximation
  - Components are arranged in order of importance, more important components come first
- Thus PCA takes the first  $k$  most important components of  $\mathbf{x}_i$  as an approximation to  $\mathbf{x}_i$



# PCA: Last Step

- Now we know how to project the data
- Last step is to change the coordinates to get final  $k$ -dimensional vector  $y$



- Let matrix  $\mathbf{E} = [\mathbf{e}_1 \cdots \mathbf{e}_k]$
- Then the coordinate transformation is  $\mathbf{y} = \mathbf{E}^t \mathbf{x}$

- Under  $\mathbf{E}^t$ , the eigenvectors become the standard basis:

$$\mathbf{E}^t \mathbf{e}_i = \begin{bmatrix} \mathbf{e}_1 \\ \vdots \\ \mathbf{e}_i \\ \vdots \\ \mathbf{e}_k \end{bmatrix} \mathbf{e}_i = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix}$$

# Recipe for Dimension Reduction with PCA

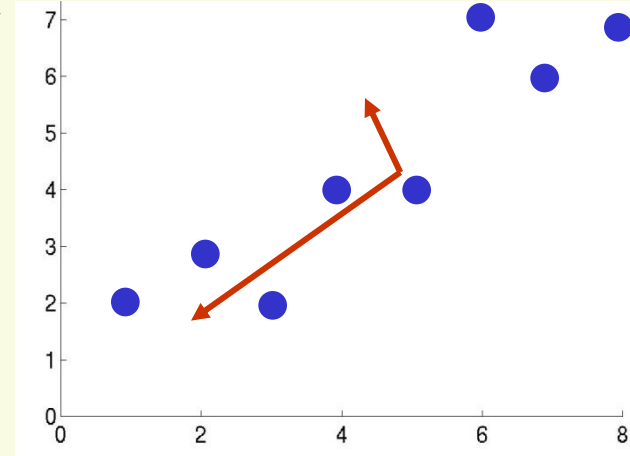
Data  $D = \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$ . Each  $\mathbf{x}_i$  is a  $d$ -dimensional vector. Wish to use PCA to reduce dimension to  $k$

1. Find the sample mean  $\hat{\boldsymbol{\mu}} = \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i$
2. Subtract sample mean from the data  $\mathbf{z}_i = \mathbf{x}_i - \hat{\boldsymbol{\mu}}$
3. Compute the scatter matrix  $\mathbf{S} = \sum_{i=1}^n \mathbf{z}_i \mathbf{z}_i^t$
4. Compute eigenvectors  $\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_k$  corresponding to the  $k$  largest eigenvalues of  $\mathbf{S}$
5. Let  $\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_k$  be the columns of matrix  $\mathbf{E} = [\mathbf{e}_1 \cdots \mathbf{e}_k]$
6. The desired  $\mathbf{y}$  which is the closest approximation to  $\mathbf{x}$  is  $\mathbf{y} = \mathbf{E}^t \mathbf{z}$

# PCA Example Using Matlab

- Let  $D = \{(1,2), (2,3), (3,2), (4,4), (5,4), (6,7), (7,6), (9,7)\}$
- Convenient to arrange data in array

$$X = \begin{bmatrix} 1 & 2 \\ \vdots & \vdots \\ 9 & 7 \end{bmatrix} = \begin{bmatrix} x_1 \\ \vdots \\ x_8 \end{bmatrix}$$



- Mean  $\mu = \text{mean}(X) = [4.6 \ 4.4]$
- Subtract mean from data to get new data array  $Z$

$$Z = X - \begin{bmatrix} \mu \\ \vdots \\ \mu \end{bmatrix} = X - \text{ repmat}(\mu, 8, 1) = \begin{bmatrix} -3.6 & -4.4 \\ \vdots & \vdots \\ 4.4 & 2.6 \end{bmatrix}$$

- Compute the scatter matrix  $S$

$$S = 7 * \text{cov}(Z) = [-3.6 \ -4.4] \begin{bmatrix} -3.6 \\ -4.4 \end{bmatrix} + \dots + [4.4 \ 2.6] \begin{bmatrix} 4.4 \\ 2.6 \end{bmatrix} = \begin{bmatrix} 57 & 40 \\ 40 & 34 \end{bmatrix}$$

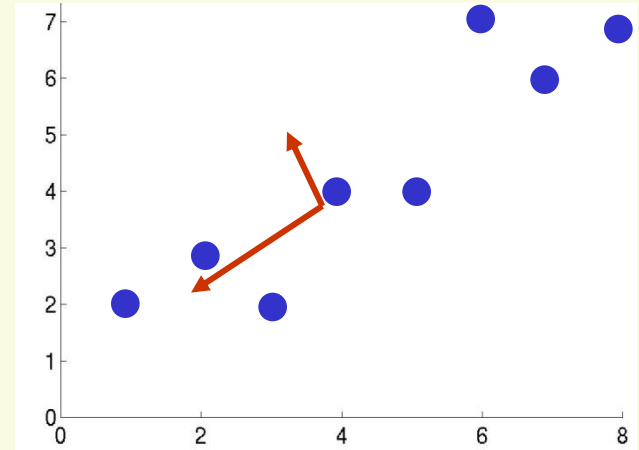
*matlab uses unbiased estimate for covariance, so  $S=(n-1)*\text{cov}(Z)$*

# PCA Example Using Matlab

- Use  $[V,D] = \text{eig}(\mathbf{S})$  to get eigenvalues and eigenvectors of  $\mathbf{S}$

$$\lambda_1 = 87 \text{ and } \mathbf{e}_1 = \begin{bmatrix} -0.8 \\ -0.6 \end{bmatrix}$$

$$\lambda_2 = 3.8 \text{ and } \mathbf{e}_2 = \begin{bmatrix} 0.6 \\ -0.8 \end{bmatrix}$$



- Projection to 1D space in the direction of  $\mathbf{e}_1$

$$\begin{aligned} \mathbf{Y} = \mathbf{e}_1^t \mathbf{Z}^t &= \left( \begin{bmatrix} -0.8 & -0.6 \end{bmatrix} \begin{bmatrix} -3.6 & \cdots & 4.4 \\ -4.4 & \cdots & 2.6 \end{bmatrix} \right) = \begin{bmatrix} 4.3 & \cdots & -5.1 \end{bmatrix} \\ &= \begin{bmatrix} y_1 & \cdots & y_8 \end{bmatrix} \end{aligned}$$