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July 1, 2015

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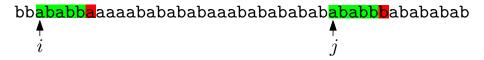
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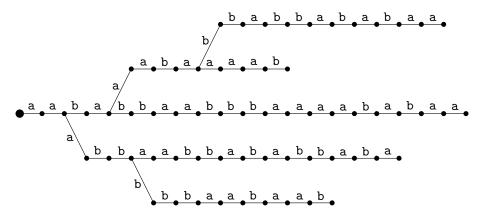
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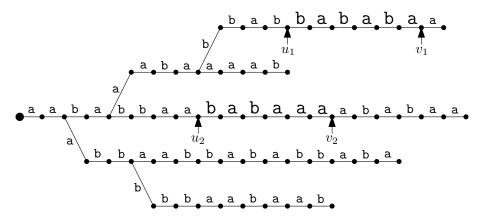
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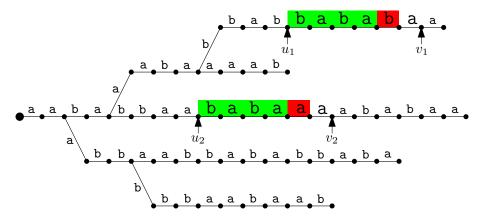
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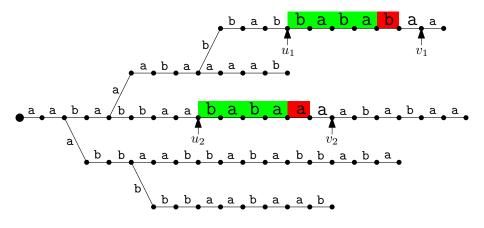


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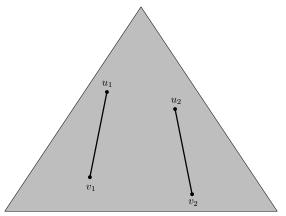






## Path-path queries

Given nodes  $u_1$ ,  $v_1$ ,  $u_2$ ,  $v_2$  such that  $u_1$  is an ancestor of  $v_1$  and  $u_2$  is an ancestor of  $v_2$ , report the longest matching prefix of paths  $u_1 \rightsquigarrow v_1$  and  $u_2 \rightsquigarrow v_2$ .

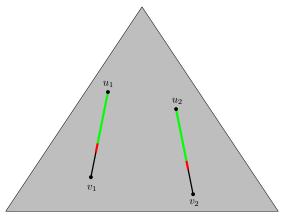


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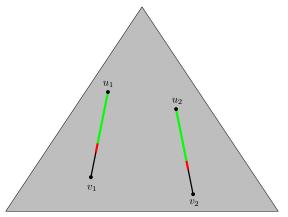


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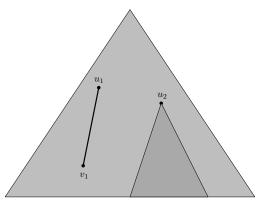


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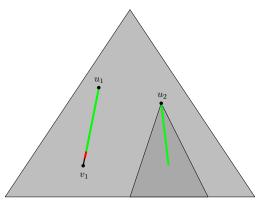


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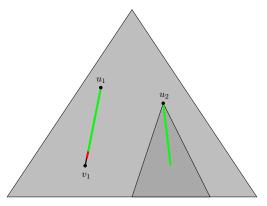


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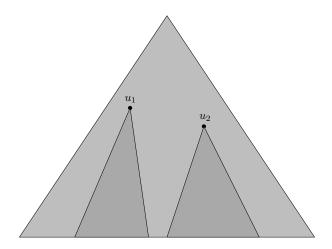


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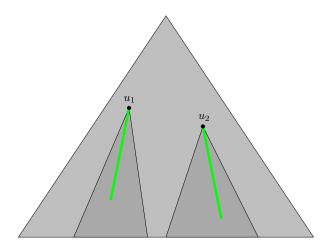
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Given nodes  $u_1, u_2$ , report the longest matching prefix of paths  $u_1 \rightsquigarrow v_1$  and  $u_2 \rightsquigarrow v_2$ , where  $v_1$  is a descendant of  $u_1$  and  $v_2$  is a descendant of  $u_2$ .



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## Results

problem	query	space	lowerbound
path-path	$\mathcal{O}(\log^* n)$	$\mathcal{O}(n)$	
path-tree	$\mathcal{O}((\log \log n)^2)$	$\mathcal{O}(n)$	predecessor hard
tree-tree	$\mathcal{O}(\textit{n}/ au)$	$\mathcal{O}(\mathbf{n} \cdot \tau)$	set-intersection hard

We start with a simple  $\mathcal{O}(1)$  query  $\mathcal{O}(n \log n)$  space solution. For every  $k = 0, 1, \ldots, \log n$ , we build a separate structure of size  $\mathcal{O}(n)$  allowing us to answer queries for paths of length  $2^k$ .

#### Structure for paths of length 2<sup>k</sup>

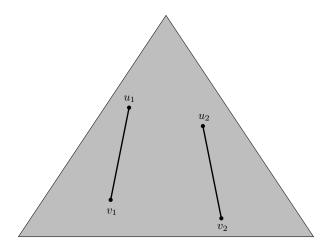
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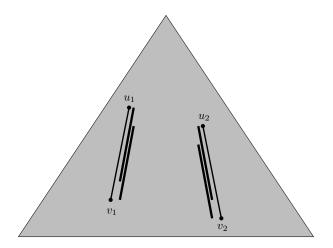
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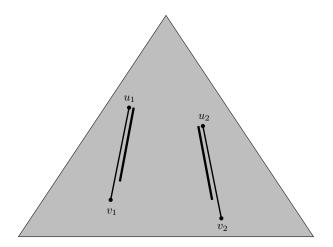
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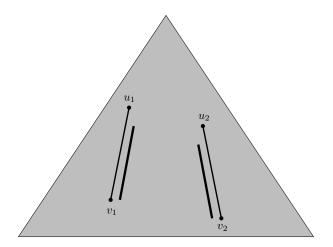
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The natural approach is to store just some of the paths of length  $2^k$ , for every *k*. To choose which paths to store, we introduce the notion of **difference covers for trees**.

#### Difference covers for trees

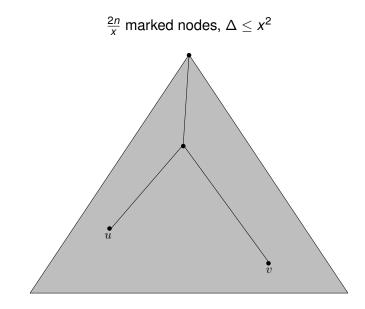
For any tree on *n* nodes and a parameter *x*, it is possible to mark  $\frac{2n}{x}$  nodes, so that for any *u*, *v* at depths  $\geq x^2$ , there exists  $\Delta \leq x^2$  such that the  $\Delta$ -th ancestors of both *u* and *v* are marked.

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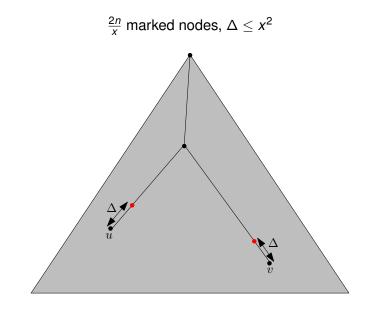
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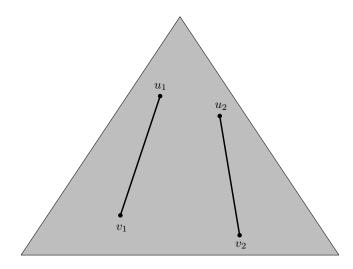
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Any query can be reduced in  $\mathcal{O}(1)$  time to computing the longest common prefix of two paths of length  $\leq \log^2 n$ .

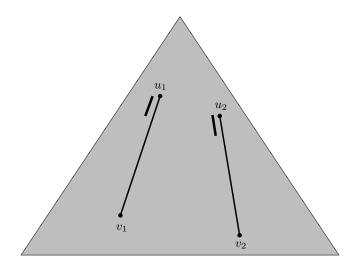
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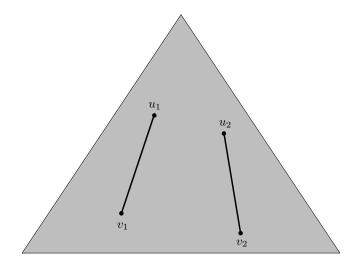
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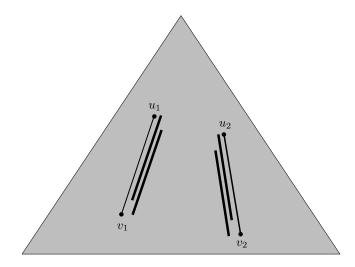
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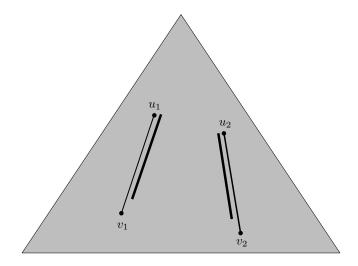
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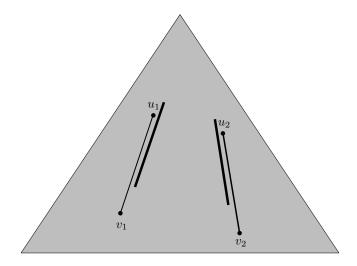
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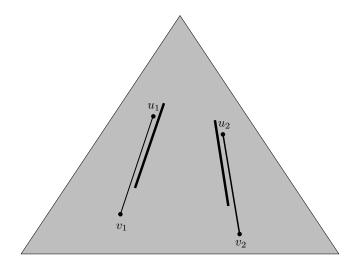
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Process the second pair of paths similarly.



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The number of iterations is at most  $O(\log^* n)$ , so after  $O(n \log^* n)$  preprocessing we can answer any query in  $O(\log^* n)$  time.

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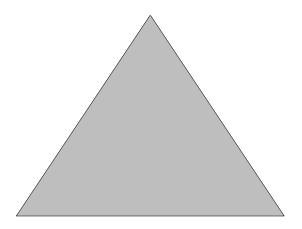
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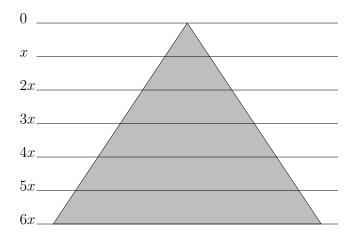
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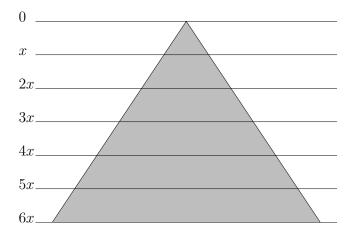
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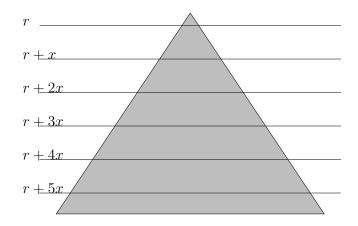
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Doesn't quite work, because we cannot guarantee that there are  $\frac{n}{x}$  such nodes.



But marking every node at depth r, r + x, r + 2x, r + 3x, ... is also enough for our purposes, where  $r \in \{0, 1, ..., x - 1\}$ .



## Trick

For at least one  $r \in \{0, 1, ..., x - 1\}$  the number of marked nodes is at most  $\frac{n}{x}$ .

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